

## Introduction to temporality in Mohawk

### 1. A DASH OF MOHAWK GRAMMAR

#### 1.0 *Linguistic type*

‘Free order’, head-marking, rich inflection, noun incorporation (*gram. polysynthetic*)

#### 1.1 *Verb template* (*FL* modulo *MB*; standard Mohawk orthography for $\wedge > \text{en}$ , $u > \text{on}$ , $l > \text{r}$ )

<u>Form(s)</u>	<u><i>FL</i> (p. 95)/<i>M&amp;W</i></u>	<u><i>MB</i></u>	<u><i>e.g.</i></u>
• <b>Slot 1</b> (opt): CATEGORY-NEUTRAL prefix:			
n-	<i>of/partitive</i> (PAR)	<i>of</i>	§1.1
sh-	<i>when/coincident</i> (COIN)	<i>wth</i> (‘with’)	
th-	<i>contrastive</i> (CON)	<i>w/o</i> (‘without’)	<i>B&amp;T</i> ‘97
• <b>Slot 2</b> (finite verb): MOOD inflection = (CL <sub>M</sub> <sup>*</sup> ) + MOOD + (CL <sub>M</sub> )			
t-	<i>duplicative</i> (DPL)	<i>plural event</i> (EE)	(1), §1.1
s-	<i>iterative</i> (ITR)	<i>part of pl event</i> ( <sup>n</sup> EE)	§1.2
ye-	<i>translocative</i> (TRANS)	<i>end of chain</i> (XX)	§1.1
te-	<i>cislocative</i> (CIS)	<i>beginning of chain</i> (XX)	§1.5
wa’-, we-, on...	<i>aorist modal</i> (AOR)	<i>indicative mood</i> (IND)	§1.1
en-, enh	<i>future modal</i> (FUT)	<i>hypothetical mood</i> (HYP)	(1), §1.6
a(h)-, ae, aon...	<i>indefinite modal</i> (IND)	<i>optative mood</i> (OPT)	(2), §1.6
te’-	<i>negative prefix</i> (NEG)	<i>irrealis mood</i> (IRR)	(2)
• <b>Slot 3</b> : Pronominal AGR with <i>subject</i> and/or <i>object</i> :			
ho-	3SM O	3sm <sub>O</sub>	§1.1
ka-	3SFN	3sf	§1.1
ske-	2s:1s	2s.1s	§1.6
⋮	⋮	⋮	⋮
• <b>Slot 4</b> : Verbal base = ({ <i>se-</i> , <i>se*-</i> }) + (n-n/v) + v-ROOT + v\√v*			
at-	<i>own, self/refl.</i> (RFL)	<i>se</i> (as in <i>de se</i> attitudes)	(2), §1.1
atat-	<i>self/reciprocal</i> (RCIP)	<i>se.se</i> (emphatic or pl <i>se</i> )	
-en	<i>be, -ed/perfective</i> (PRF)	<i>be</i>	§1.1
-‘	<i>begin/inchoative</i> (INC)	<i>begin</i>	
-hákye	<i>go.along/prog.</i> (PRG)	<i>prg</i> (‘progressive’)	§1.1
-k	<i>continue/continuative</i> (CNT)	<i>itr</i> (‘iterative’)	(2)
-ha	<i>go.and</i>	<i>go.to</i>	§1.6
-hser	<i>going.to/purposive</i> (PURP)	<i>intend</i>	(2)
⋮	⋮	⋮	⋮
• <b>Slot 5</b> : ASPECT inflection = { <sup>o</sup> }+ASPECT + ( <sup>o</sup> , {-[, -]})			
-(n)e’, -‘...’	<i>punctual aspect</i> (PNC)	<i>eventive aspect</i> (EVT)	§1.1
-(h)s, -ha’, ...	<i>serial aspect</i> (SRL)	<i>durative aspect</i> (DUR)	§1.1
-on, -en, -‘, ...	<i>perfective aspect</i> (PRF)	<i>stative aspect</i> (STA)	§1.3, §1.4
-hne’	<i>former past</i> (PST)	<i>perfective aspect</i> ( <sup>n</sup> PRF)	<i>B&amp;T</i> ‘98
-kwe’	<i>remote past</i> (PST)	<i>used to-aspect</i> ( <sup>h</sup> PRF)	<i>B&amp;T</i> ‘98

- (1)
- B&T*
- (4):
- Describing an old fire truck, with no place to hook up the hose:*

Onenk tsi ki tehniyahse ohnaken en-t-hy-atyen-<sup>6</sup>  
*necessary* D<sub>⊥</sub> N *two.people behind* HYP-EE-33m-sit-EVT  
 FUT-DPL-3dM-sit-PNC

MB  
 M&W/B&T

It was necessary for two people to sit behind...

tanon en-hni-yena-<sup>7</sup> ne ohonrota.  
*and* HYP-33m.3s-hold-EVT D<sub>⊥</sub> *hose*  
 FUT-3dM.3s-hold-PNC

MB  
 M&W

and hold the hose.

- (2)
- M&W*
- (58):
- Fox enlists Cat for his fight with Bear, but when they arrive, Bear offers peace.*

*Fox says 'Ok by me', but Cat speaks up:*

kwahi:ken ki<sup>8</sup> n=i<sup>9</sup>i tsi wa'-ke-hnáten  
*very* N D<sub>⊥</sub>=me D<sub>⊥</sub> IND-1s-be.sorry.EVT  
 AOR-1s-be.sorry-PNC

MB  
 M&W

I am very sorry...

tsi iyah te-tew-ate-riyo-hser-e'  
 D<sub>⊥</sub> *not* IRR-122-se-thrash-intend-STA  
 neg-1pI-RFL-fight-PURP-PRF

MB  
 M&W

...that we're not going to fight.

(59) *Then Cat said further:*

ken<sup>10</sup> n=i<sup>11</sup> n-aon-k-yér-en  
*emp* D<sub>⊥</sub>=me of-OPT-1s-do-STA  
 PAR-IND.1s O-do-PRF

MB  
 M&W

As for me, this is what I would've done<sup>1</sup>(wanted to do)...

ne toka a-yunkw-ate-ríyo-k-e'  
 D<sub>⊥</sub> *if* OPT-122-se-thrash-itr-EVT  
 IND-1pI-RFL-fight-state-PNC

MB  
 M&W

...if we had fought<sup>1</sup>(opted to fight).

## 1.2 MOOD *interacts with* ASPECT (according to *B&T*)

	<u>-EVT</u>	<u>-DUR</u>	<u>-STA</u>	
• ∅	* (?)	✓ (1)	✓ (3)	<i>M&amp;W</i> (53)?
• <u>IND-</u>	✓ (1)	*	* (?)	<i>M&amp;W</i> (51)?
• <u>HYP-</u>	✓ (6)	✓	✓	
• <u>OPT-</u>	✓ (6)	✓	✓ (59)	
• <u>IRR-</u>	*	*	✓ (58)	

## REMARKS:

- Only *events/processes* (EVT) can be reported as *facts* (IND) (*like* Yukatek, *unlike* Kalaallisut)
- *Non-events* (DUR/STA) do not inflect like ‘proper verbs’ (MOOD optional) (*like* Yukatek (MOOD impossible), *unlike* Kalaallisut (MOOD obligatory))
- *Negation* requires *non-factual mood* (IRR or CF-SBJ) (*like* Kalaallisut (IRR or NON), *unlike* English)
- *Irrealis* talk requires reference to a *state* (of unrealized expectation?) (*unlike* Kalaallisut)
- *Future* talk does NOT require reference to a *state* (of future-oriented attitude) (*like* English, *unlike* Kalaallisut & Yukatek)

## HYPOTHESIS:

IND in Mohawk	~	reality presupposition	(like IND in Kal, Yukatek, etc)
IRR in Mohawk	~	<i>state</i> of unrealized expectation	(like <i>prospective statives</i> in Kal, Yuk.)
HYP in Mohawk	~	realistic hypothesis (‘prospect)	(like WILL/WOULD – TNS presup. in Eng)
SBJ in Mohawk	~	<sup>1</sup> (more remote) possibility	(like SBJ in Polish, etc)

## 2. BEGINNING OF SAMPLE TEXT

**Ohkwari tánon’ jítson**  
“The Bear and the Fox”

In Mithun, M. & Woodbury, H. eds. 1980 *Northern Iroquoian Texts*, 77–95, U. Chicago Press.

REVISED TRANSCRIPTION:  $\wedge > \text{en}$ ,  $u > \text{on}$ ,  $j > \text{ts}$ ,  $l > \text{r}$ , as in standard Mohawk orthography.

REVISED TRANSLATION: Floyd Lounsbury (*FL*) 1953 modulo M. Bittner (*MB*) 3/31/2005.

§1. *Fox finds food and shares it with Bear*

- §1.1 ki tsitsho te-ho-t-stikahwh-en-hákie-‘ if  
 N fox EE-3sm-se-travel-be-prg-STA  
 A fox was travelling along, when...  
 thontaiawénhstsi yah-à-ra-w-e’ ib, mf  
 suddenly XX-IND-3sm-arrive-EVT  
 ...suddenly he came upon...  
 tsi-nón ni-ka-ya’kyónni ko-hsaten-s yó-tá’-s ff  
 D<sub>1</sub>-place of-3sf-lie.down.EVT 3s.3s-straddle-DUR 3sf<sub>U</sub>-sleep-DUR  
 ...a sleeping mare.
- §1.2 wa-ha-non’-kéra-‘ ki ko-hsá:ten-s mf<sub>1</sub>, ff<sub>1</sub>  
 IND-3sm-milk-drink-EVT N 3s.3s-straddle-DUR  
 He sucked milk from the mare...  
 tsi=ni-yó-re-‘ y-a-hó-hta’-ne’ if<sub>2</sub> mf<sub>2</sub>  
 D<sub>1</sub>=of-3s-distance-CL XX-IND-3sm<sub>U</sub>-eat.one’s.fill-EVT  
 ...until he was full...

- tánon' stónha y-onsa-h-at-énna't-e'  
*and little.bit* XX-<sup>n</sup>EE.IND-3sm-*se-take.snack*-EVT  
 ...and then took a little bit away for a snack.
- §1.3 kwah ken ni-yo-ré-'a n-ye-s-haw-én-on *if*  
*just bit of-3s-distance-DIM of-XX-<sup>n</sup>EE-3sm-go-STA*  
 He had just gone a short distance,...
- tho o-hkwári wa-t-hy-áte-ra'-ne' *ib, mf*  
*there sg-bear IND-EE-33m-se-come.upon-EVT*  
 ...when he met a bear.
- §1.4 wa-hèn-ron-' n=o-hkwári: *mf, ff*  
 IND-3sm-*say*-EVT D<sub>T</sub>=*sg-bear*  
 The bear said:  
 “nah-òten ne' thíken sa-hnoskw-á-hnont-e'?” *if, ib, mf*  
 “*thing-kind* D<sub>T</sub> *that* 2s<sub>U</sub>-*cheek.cavity-n/v-have.full.cheeks*-STA  
 “What is that stuff bulging in your cheeks?”
- §1.5 wa-hèn-ron-' ne tsitsho *mf, ff*  
 IND-3sm-*say*-EVT D<sub>T</sub> *fox*  
 The fox said:  
 “ko-hsáten-s ise-nekwá k-yó-ta'-s *if*  
 “3s.3s-*straddle-DUR there-direction* XX-3sf<sub>U</sub>-*sleep*-DUR  
 “There is a mare, over there, sleeping,...
- y-a'-ke-non'-kéra-' *mf*  
 XX-IND-1s-*milk-drink*-EVT  
 ...I sucked milk from her.”
- §1.6 “owá” wa-hèn-ron-' ki o-hkwári. *if, mf, ff*  
*Gosh!* IND-3sm-*say*-EVT N *sg-bear*  
 “Gosh!” said the bear.  
 “ká-ti' en-ske-natón-ha-hs-e' *if, mf*  
 “wh-*how* HYP-2s.1s-*show-go.to-dat*-EVT  
 “How about showing me...  
 ka'-nón ni-yó-ta'-s *ff*  
 wh-*place of-3sf<sub>U</sub>-sleep*-DUR  
 ...where she's sleeping,...
- aón-to *mf*  
 OPT.3s-*be.possible*.STA  
 ...[then] it would be possible...
- n-í:'i a-ie-non'-kéra-' óni *if mf ff*  
 D<sub>T</sub>=*me* OPT-1s-*milk-drink*-EVT *also*  
 ...for me to suck too.”

## Formalization (1): Indicative Mohawk discourse online

### 1. KEY PLAYERS IN TEMPORAL ANAPHORA (in the order of appearance):

Form            MB gloss (stands for)    1st ex    Presuppositional test (<sup>P</sup>); update; implicature (<sup>I</sup>)

**V-slot 1** (opt): CATEGORY-NEUTRAL prefix:

<i>n-</i>	<i>of</i>	§1.1	$[e  d\kappa^\pi\{e\} =_{d\Omega} d\pi]$	
		§1.3	$[k^\pi  d\varepsilon\varepsilon: k^\pi\{\varepsilon\} =_{d\Omega} \Pi\{\varepsilon\}]$	
		§1.2	$[k^\pi  d\varepsilon\varepsilon: k^\pi\{\varepsilon\} =_{d\Omega} \Theta\{\varepsilon\}]$	
<i>sh-</i>	<i>with</i> ('with')	§4.3		
<i>th-</i>	<i>w/o</i> ('without')	§2.6		

**V-slot 2** (finite V): MOOD inflection = (CL<sub>M</sub><sup>\*</sup>) + MOOD + (CL<sub>M</sub>)

<i>t(e)-</i>	EE (pl. event: process, §1.1	§1.1	$[eel\ prc_{d\Omega}\ ee]$	
	or reciprocal) §1.3	§1.3	$[eel\ rcp_{d\Omega}\ ee]$	
<i>(t)s-</i>	"EE (part of pl. event) §1.2 <sup>3</sup>	§1.2 <sup>3</sup>	$[\mathcal{E}\mathcal{E}  d\exists = {}^1\mathcal{E}\mathcal{E}]$	
<i>y(e)-</i>	XX (end of chain) §1.1	§1.1	$[  d\varepsilon = {}^f d\varepsilon\varepsilon]$	
<i>t(e)-</i>	XX (beg. of chain) §1.5	§1.5	$[s  s \subseteq_{d\Omega} {}^1 d\pi\pi]$	
<i>wa'-</i>	IND (indicative) §1.1	§1.1	$[  \vartheta_{d\Omega} d\varepsilon < \vartheta_{d\omega} d\varepsilon]$	(realized <i>event</i> )
	§1.2 <sup>1</sup>	§1.2 <sup>1</sup>	$[  \vartheta_{d\Omega} {}^1 d\varepsilon\varepsilon < \vartheta_{d\omega} d\varepsilon]$	(realized <i>1st</i> of <i>event-chain</i> )
	§1.2 <sup>3</sup>	§1.2 <sup>3</sup>	$[  \vartheta_{d\Omega} {}^1 d\exists < \vartheta_{d\omega} d\varepsilon];$	(realized <i>1st</i> of <i>planned ev's</i> )
	(1)	(1)	$[  \vartheta_{d\Omega} {}^1 d\eta^\varepsilon < \vartheta_{d\omega} d\varepsilon]$	(realized <i>1st</i> of <i>habitual ev's</i> )
<i>en-</i>	HYP (hypothetical) §1.6	§1.6		
<i>a-</i>	SBJ (subjunctive) §1.6	§1.6		
<i>te-</i>	IRR (irrealis) §2.6	§2.6		

**V-slot 3:** Pronominal AGR with S, O

⋮

**V-slot 4:** V.BASE = ({*se, se.se*}) + (n + n/v +) v (+ v\v)

<i>at-</i>	<i>se-</i>	§1.1	$[  AG d\varepsilon\varepsilon =_{d\Omega} DA \{RS d\varepsilon\varepsilon\}]$
<i>-stikahwah-</i>	<i>-go.along-</i>	§1.1	$[k^\pi  d\varepsilon\varepsilon: AG\ go.along_{d\Omega} k^\pi]$
<i>-en, -on</i>	<i>-be</i>	§1.1	$[s  DA s =_{d\Omega} AG d\varepsilon\varepsilon]$
<i>-hakie</i>	<i>-prg</i>	§1.1	$[  d\sigma =_{d\Omega} RS {}^1 d\varepsilon\varepsilon]$
⋮	⋮	⋮	⋮

**V-slot 5:** ASPECT infl = ASPECT + (CL<sub>A</sub>)      asp-adjustment;    <sup>T</sup>τω-location;    pre-fb <sup>T</sup>τ-update

<i>-(e)', -ne</i>	EVT (eventive) §1.1	§1.1	$([e  e =_{d\Omega} BG d\sigma];)$	$[  d\varepsilon \subseteq_{d\Omega} d\tau];$	$[t  t =_{d\Omega} \Theta RS d\varepsilon]$
		§1.2 <sup>1</sup>	$([  d\varepsilon\varepsilon \in_{d\Omega} d\eta^{\varepsilon\varepsilon}];)$	$[  {}^1 d\varepsilon\varepsilon \subseteq_{d\Omega} d\tau];$	$[t  t =_{d\Omega} \Theta RS {}^1 d\varepsilon\varepsilon]$
<i>-(h)s, -ha</i>	DUR (durative) §1.1	§1.1	$([s  s =_{d\Omega} RS d\varepsilon];)$	$[  d\tau \subseteq_{d\Omega} d\eta^\varepsilon];$	$[\mathcal{D}  \mathcal{D} = \Theta RS d\eta^\varepsilon]$
		§1.1	$([s  s =_{d\Omega} RS d\varepsilon];)$	$[  d\tau \subseteq_{d\Omega} d\sigma];$	
<i>-(en), -on</i>	STA (stative) §1.1	§1.1	$([s  s =_{d\Omega} RS d\varepsilon];)$	$[  d\tau \subseteq_{d\Omega} d\sigma];$	
<i>-s-kwe'</i>	<sup>h</sup> PRF ('used to') BT98	BT98	$[s  BG s =_{d\omega} BG RS {}^f d\eta^\varepsilon];$	$[  d\tau \subseteq_{d\omega} d\sigma];$	
<i>-en-hne'</i>	<sup>n</sup> PRF (nth result state) BT98	BT98	$[s  s =_{d\omega} RS {}^n d\varepsilon\varepsilon];$	$[  d\tau \subseteq_{d\omega} d\sigma];$	

## 2. KEY PLAYERS IN NOMINAL ANAPHORA (in default order)

**N-determiners**

<i>ne(n)</i>	N <sub>T</sub>	§1.2	[  <b>d</b> α = <sub>dΩ</sub> dκ <sup>α</sup> {dεε}]
<i>tsi</i>	N <sub>⊥</sub>	§1.1	[ l l = <sub>dΩ</sub> dκ <sup>π</sup> {dε}]
<i>ki'</i>	N	§1.1	[ <b>a</b> k <sup>α</sup> l <b>a</b> = k <sup>α</sup> { <b>d</b> ε}]
<i>tho</i>	K	§1.3	[ <b>k</b> <sup>α</sup> al a = <sub>dΩ</sub> <b>k</b> <sup>α</sup> {dε}]

**V-slot 3:** Pronominal V.AGR with S, O

3sm <sub>U</sub>	§1.1	<sup>P</sup> [  3sm <b>d</b> α]; [  DA dε = <sub>dΩ</sub> <b>d</b> α]
2s.1s	§1.6	<sup>P</sup> [  2s <b>d</b> α, 1s dα]; [  AG dε = <sub>dΩ</sub> <b>d</b> α, DA dε = <sub>dΩ</sub> dα]

## 3. IROQUOIAN INDICATIVE: REALIZED (FIRST) EVENT

- Realized (simple) *event*  
e.g. §1.1 ('arrive')
- Realized *Ist* of *event-chain*  
e.g., §1.2<sup>1</sup> ('suck milk')
- Realized *Ist* of *planned events*  
e.g., §1.2<sup>3</sup> ('take a little bit for a snack')
- Realized *Ist* of *habitual events* (i.e. evt. need not be 'specific', *contra* Baker & Travis '97, '98)

(1) Habit still current **now**:

*Hello Karen. What do you want me to do for you? You want me to tell you a story.*

*Oneidas don't tell stories in the spring time.*

Kwah kens ne' ok t-on.s.a-ka-nyey-a-hkw-e' KM

*just HAB D<sub>T</sub> emp EE-<sup>n</sup>EE-IND-3s-snow-n/v-go.away-EVT* MB

P P P P DU-ITER.AOR-NS-snow-JOIN-pick.up-PUNC KM

As soon as the snow goes away,...

o-khna' ne' wa'-hron-at-kenhra't-e' KM

*emp-then D<sub>T</sub> IND-333m-se-stop-EVT* MB

...they stop. KM

(Oneida: Karin Michelson 1981, p. 36)

(2) Habit still current **then**:

tsi' ke-ks-a' k-ehyahr-e' KM

**D<sub>⊥</sub> 1s-child-CL 1s-remember-STA** MB

When I was a child, I remember... KM

kens tsi's n-a'-k-at-shanoni-' KM

**HAB so of-IND-1s-se-be.happy-EVT** MB

...I used to be so glad KM

n=are' s-a-yo-hsr-at-e' KM

**D<sub>T</sub>=again XX-IND-3s-winter-n/v-be.there-EVT** MB

...when winter came. [I would (HYP) hear the elders tell stories again.] KM

(Oneida: Karin Michelson 1981, p. 36)

4. *-hne'/-kwe'*: PERFECTIVE ASPECT vs. PAST TENSE/ANAPHOR• **Three analyses:**

	STA- <i>hne'</i>	DUR- <i>kwe'</i>
Lounsbury 1953:	'remote past'	'former past'
Baker & Travis 1998	<i>back then</i> (STA allomorph)	<i>back then</i> (DUR allomorph)
Bittner 2005	"PRF (nth result state)	AFT (after-state: 'used to')

• **Argument 1:**

*-hne'/-kwe'* (i) occur in the *slot for aspect inflection* and (ii) *require stative/durative aspect*. This is mysterious if *-hne'/-kwe'* are past tenses/anaphors (in an otherwise tenseless system), but natural they are part of this aspectual system:

Form(s)	MB gloss	1st ex	asp-adjustment	$\tau\omega$ -location	pre- <i>fb</i> $\tau$ -update
<i>-(e)'</i> , <i>-ne</i>	EVT (eventive)	§1.1	([ <i>el e</i> = <sub>dΩ</sub> BG <i>dσ</i> ];)	[ <i>dε</i> ⊆ <sub>dΩ</sub> <b>dτ</b> ];	[ <b>t</b>   <b>t</b> = <sub>dΩ</sub> $\vartheta$ RS <i>dε</i> ]
		§1.2 <sup>1</sup>	([ <i>dεε</i> ∈ <sub>dΩ</sub> <i>dη<sup>εε</sup></i> ];)	[ <sup>1</sup> <i>dεε</i> ⊆ <sub>dΩ</sub> <b>dτ</b> ];	[ <b>t</b>   <b>t</b> = <sub>dΩ</sub> $\vartheta$ RS <sup>1</sup> <i>dεε</i> ]
<i>-(h)s</i> , <i>-ha</i>	DUR (durative)	§1.1		[ <b>dτ</b> ⊆ <sub>dΩ</sub> <i>dη<sup>ε</sup></i> ];	[ $\varnothing$   $\varnothing$ = $\vartheta$ RS <i>dη<sup>ε</sup></i> ]
		§1.1	([ <i>s</i>   <i>s</i> = <sub>dΩ</sub> RS <i>dε</i> ];)	[ <b>dτ</b> ⊆ <sub>dΩ</sub> <i>dσ</i> ];	
<i>-(en)</i> , <i>-on</i>	STA (stative)	§1.1	([ <i>s</i>   <i>s</i> = <sub>dΩ</sub> RS <i>dε</i> ];)	[ <b>dτ</b> ⊆ <sub>dΩ</sub> <i>dσ</i> ];	
<i>-s-kwe'</i>	<sup>h</sup> PRF ('used to')	BT98	[ <i>s</i>   BG <i>s</i> = <sub>dΩ</sub> BG RS <sup>f</sup> <i>dη<sup>ε</sup></i> ];	[ <b>dτ</b> ⊆ <sub>dΩ</sub> <i>dσ</i> ];	
<i>-en-hne'</i>	"PRF (nth result state)	BT98	[ <i>s</i>   <i>s</i> = <sub>dΩ</sub> RS "dεε];	[ <b>dτ</b> ⊆ <sub>dΩ</sub> <i>dσ</i> ];	

• **Argument 2:**

According to Baker & Travis 1998, *-hne'/-kwe'* is interpreted like *back then* and *requires an antecedent* (temporal adverbial or prior *-hne'/-kwe'*). This requirement would be unexpected for perfective aspect and, in fact, is NOT borne out by *evidence from texts*.

- (3) Ka-rhá:-kon t-hati-'terón:t-ah-kwe' iá:-k-en' ki:-ken kahwá:tsire'.  
 sg-forest-LOC EE-333m-live-DUR-<sup>h</sup>PRF 3s-say-PRF *this family*  
 In a forest, 'tis said, there used to live this family. (Mohawk, KO, p. 102)

- (4) *It is said that...*

tsi ki:ken kén' nit-ho-ionha onkwe-hón:we  
 N<sub>↓</sub> *this bit of-3sm-age native-person*  
 ...there was this Indian youth who...

ra-on'eskwaní-hah-kwe' iot-ahsont-atíhen shé:kon a-ho-iak-en-hatié-se-k-e'  
 3sm<sub>U</sub>-enjoy-DUR-<sup>h</sup>PRF sg-night-middle still OPT-3sm-go.out-be-prg-itr-EVT  
 ...used to enjoy going out till after midnight. (Mohawk, KO, p. 238)

• **Argument 3:**

*Counterfactual -hne'*: clearly non-past, but plausibly perfective (in (5), tree no longer exists).

- (5) Tóka aon-sa-k-at-káhto-' aon-sa-k-yentere'-ne' ne ó-kwir-e.  
*if* OPT-"EE-1s-se-look-EVT OPT-"EE-1s-know-STA."PRF N<sub>↑</sub> sg-tree-CL  
 If I saw it again, I would remember (*lit.* would've known) the tree. (Mohawk, B&T 97:250)

## APPENDIX: INDICATIVE MOOD

§1.1–1.5 *Fox finds food and shares it with Bear*(•) *Speech start-up*[**w e l e**: AG *speak.up<sub>w</sub>*]; [**t l t** =<sub>d<sub>ω</sub></sub> **ϑ d ε**];reality <sup>τ</sup>w\*:

- <sup>τ</sup>e\*: speech event
- | <sup>τ</sup>t\*: e\*-now

## 1.1 A fox...

*if: if*

ki                      tsitsho

N                        fox

[**a**  $k^α$  | **a** =  $k^α$ {**dε**}]; [| fox  $dk^α$ ]; [**p l p** = Dom  $dk^α$ ];

...on the move...

*if: mf*

te-

EE-

[**e e l p r c**<sub>d<sub>Ω</sub></sub> **e e**]; (<sup>Δ</sup>[**t l t** =<sub>d<sub>Ω</sub></sub> RS <sup>1</sup>**dεε**];)

ho-

3sm<sub>U</sub>-<sup>P</sup>[| 3sm<sub>d<sub>Ω</sub></sub> **dα**]; [| DA {RS **dεε**} =<sub>d<sub>Ω</sub></sub> **dα**];

t-

-stikahwah

se-

-go.along

[| AG **dεε** =<sub>d<sub>Ω</sub></sub> DA {RS **dεε**}]; [ $k^π$  | **dεε**: AG *go.along*<sub>d<sub>Ω</sub></sub>  $k^π$ ];

-en

-hákie

-be

-prg

[| s | DA **s** =<sub>d<sub>Ω</sub></sub> AG **dεε**]; [| **dσ** =<sub>d<sub>Ω</sub></sub> RS <sup>1</sup>**dεε**]

-‘

-STA

[| **dτ**  $\subseteq_{d\Omega}$  **dσ**];reality <sup>τ</sup>w\*:

- <sup>τ</sup>e\*: speech event
- | <sup>τ</sup>t\*: e\*-now

 $w_0 \in {}^\tau p_0$  $(p_0$ -story world)

••...

 $ee_1$ :  $k^α$ -fox  $a_1$  goes along  $k^π$ -path

||

<sup>τ</sup>t<sub>1</sub> =  $\vartheta_{w_0}$  RS<sub>w<sub>0</sub></sub><sup>1</sup> $ee_1$ : result time of  $ee_1$ -dep.

=

 $s_1$  = RS<sub>w<sub>0</sub></sub><sup>1</sup> $ee_1$ : result state of  $ee_1$ -departure

- 1.1 ...suddenly *ib*  
 thontaiawéhstsi  
*suddenly*  
 $[e | e \in d\varepsilon\varepsilon]; [\mathbf{t} | \mathbf{t} =_{d\Omega} \vartheta d\varepsilon];$
- ...came upon *mf*  
 yah-                    à-  
 XX-                    IND-  
 $[ | d\varepsilon =_{d\Omega} {}^f d\varepsilon\varepsilon]; [ | \vartheta_{d\Omega} d\varepsilon < \vartheta_{d\omega} \mathbf{d}\varepsilon];$
- ra-  
 3sm-  
 ${}^P [ | 3sm_{d\Omega} \mathbf{d}\alpha]; [ | AG d\varepsilon =_{d\Omega} \mathbf{d}\alpha];$
- we-  
 -arrive  
 ${}^P [ | d\varepsilon\varepsilon: AG go.along_{d\Omega} d\kappa^\pi]; [ | d\varepsilon = {}^f d\varepsilon\varepsilon];$   
 -'  
 -EVT  
 $[ | d\varepsilon \subseteq_{d\Omega} \mathbf{d}\tau]; [\mathbf{t} | \mathbf{t} =_{d\Omega} \vartheta RS d\varepsilon];$
- ...a place *ff*  
 tsi-                    nón  
 $D_{\perp}$ -                    *place/time*  
 $[ | l =_{d\Omega} d\kappa^\pi \{d\varepsilon\}]; [ | \Pi \{\varepsilon\} \subseteq d\kappa^\pi \{\varepsilon\}]$
- ...where a mare was lying down...  
 ni-                    ka-  
 of-                    3sf-  
 $[e | d\kappa^\pi \{e\} =_{d\Omega} d\tau]; {}^P [ | \mathbf{k}^\alpha | 3sf_{d\Omega} \mathbf{k}^\alpha \{d\varepsilon\}]; [ | AG d\varepsilon =_{d\Omega} \mathbf{d}\kappa^\alpha \{d\varepsilon\}];$
- ya'kyónni-                    -Ø  
*lie.down*                    -STA  
 $[ | d\varepsilon: AG lie.down_{d\Omega}]; [s | s =_{d\Omega} RS d\varepsilon]; [ | \mathbf{d}\tau \subseteq_{d\Omega} d\sigma];$
- ko-  
 3s.3s-  
 ${}^P [ | 3s AG d\eta^\varepsilon, 3s \mathbf{d}\kappa^\alpha \{d\eta^\varepsilon\}]; [ | DA \{d\eta^\varepsilon\} = \mathbf{d}\kappa^\alpha \{d\eta^\varepsilon\}];$
- hsaten-                    -s  
*ride.astride*                    -DUR  
 $[ | d\eta^\varepsilon: AG ride.astride DA]; [ | \mathbf{d}\tau \subseteq_{d\omega} d\eta^\varepsilon];$
- ...asleep.  
 yó-                    -tá'                    -s  
 3sf<sub>U</sub>-                    -sleep-                    -DUR  
 ${}^P [ | 3sf_{d\Omega} \mathbf{d}\kappa^\alpha \{d\sigma\}]; [ | DA d\sigma =_{d\Omega} \mathbf{d}\kappa^\alpha \{d\sigma\}]; [ | d\sigma: DA sleep_{d\Omega}]; [ | \mathbf{d}\tau \subseteq_{d\Omega} d\sigma];$

---

$w_0 \in {}^\top p_0$	( $p_0$ -story worlds)
••...•	$ee_1: k_1^\alpha$ -fox $a_1$ goes along $k_1^\alpha$ -path
	$t_1 = \vartheta_{w_0} \text{RS}_{w_0}^1 ee_1$ : result time of $ee_1$ -dep.
=	$s_1 = \text{RS}_{w_0}^1 ee_1$ : result state of $ee_1$ -departure
•	$e_1 = {}^f ee_1$ : $ee_1$ -end; fox $a_1$ arrives at $l_1$
	$t'_1 = \vartheta_{w_0} e_1$ : $e_1$ -time
	${}^\top t''_1 = \vartheta_{w_0} \text{RS}_{w_0} e_1$ : $e_1$ -arrival result time
•	$e'_1: k_1^\alpha$ -mare lies down in $l_1$
===...	$s'_1 = \text{RS}_{w_0} e'_1$ : $k_1^\alpha$ -mare is still lying in $l_1$ $k_1^\alpha$ -mare is asleep

1.2<sup>1</sup> He sucked milk from...*mf*<sub>1</sub>

wa-

IND-

[*eel*]; [ $\vartheta_{d\Omega}^1 d\varepsilon\varepsilon < \vartheta_{d\Omega} d\varepsilon$ ];

ha-

3sm-

<sup>p</sup>[ $l$  3sm  $d\alpha$ ]; [ $l$  AG  $d\varepsilon\varepsilon =_{d\Omega} d\alpha$ ];

non'-

-ké:ra-

*milk.of-*

-drink.from-

[ $k^\beta | k^\beta$  *milk.of*  $d\kappa^\alpha$ ]; [ $h^{\varepsilon\varepsilon} | h^{\varepsilon\varepsilon}$ : AG *drink*  $d\kappa^\beta$  *from*  $d\kappa^\alpha$ ];

-‘

-EVT

[ $l$   $d\varepsilon\varepsilon \in_{d\Omega} d\eta^{\varepsilon\varepsilon}$ ]; [ $l$   ${}^1 d\varepsilon\varepsilon \subseteq_{d\Omega} d\tau$ ]; [ $tl$   $t =_{d\Omega} \vartheta \text{RS}^1 d\varepsilon\varepsilon$ ]

...the mare

*fb*<sub>1</sub>

ki

N

[ $al$   $a =_{d\Omega} d\kappa^\alpha \{d\varepsilon\varepsilon\}$ ];

ko-

3s.3s-

<sup>p</sup>[ $l$  3s AG  $d\eta^\varepsilon$ , 3s  $d\kappa^\alpha \{d\eta^\varepsilon\}$ ]; [ $l$  DA  $\{d\eta^\varepsilon\} = d\kappa^\alpha \{d\eta^\varepsilon\}$ ];

hsaten-

-s

*ride.astride*

-DUR

[ $l$   $d\eta^\varepsilon$ : AG *ride.astride* DA]; [ $l$   $d\tau \subseteq_{d\omega} d\eta^\varepsilon$ ];

1.2<sup>2</sup> ...until*if*<sub>2</sub>

tsi=

D<sub>⊥</sub>=[el e = <sup>f</sup>dεε];

ni-

yó-

of-

3s<sub>U</sub>-[k<sup>τ</sup> dεε: k<sup>τ</sup>{ε} =<sub>dΩ</sub> ϑ{ε}]; <sup>P</sup>[l 3s dτ]; [l dk<sup>τ</sup>{<sup>2</sup>dεε} =<sub>dΩ</sub> dτ];

re-

-‘

*distance-*

-CL

[l <sup>2</sup>dεε <<sub>dΩ</sub> dε]; [tl t =<sub>dΩ</sub> dk<sup>τ</sup>{dε}]

...he had his fill

*mf*<sub>2</sub>

y-

a-

XX-

IND-

[l dε = <sup>f</sup>dεε]; [l ϑ<sub>dΩ</sub> dε < ϑ<sub>dω</sub> dε];

hó-

3sm<sub>U</sub>-<sup>P</sup>[l 3sm dα]; [l DA {RS dε} =<sub>dΩ</sub> dα];

-hta’-

-eat.one’s fill-

<sup>P</sup>[l (dεε: AG *feed*<sub>dΩ</sub>), dε = <sup>f</sup>dεε]; [l RS dε: DA *feel.full*<sub>dΩ</sub>];

-ne’

-EVT

[l dε ⊆<sub>dΩ</sub> dτ]; [tl t =<sub>dΩ</sub> ϑRS dε]; $w_0 \in {}^T p_0$   
⋮ $(p_0$ -story worlds)  
⋮

•

 $e_1 = {}^f ee_1$ :  $ee_1$ -end; fox  $a_1$  arrives at  $l_1$ 

||

 $t'_1 = \vartheta_{w_0} e_1$ :  $e_1$ -time

||

 $t''_1 = \vartheta_{w_0} RS_{w_0} e_1$ :  $e_1$ -arrival result time

•

 $e'_1$ :  $k^{\alpha}_1$ -mare lies down in  $l_1$ 

===...

 $s'_1 = RS_{w_0} e'_1$ :  $k^{\alpha}_1$ -mare is still lying in  $l_1$  $k^{\alpha}_1$ -mare is asleep

1

••...•

 $ee_2$ : fox  $a_1$   $h^{\varepsilon\varepsilon}_2$ -sucks  $k^{\beta}_2$ -milk from  $k^{\alpha}_1$ -mare  $a_2$ 

2

•

 $e_2 = {}^f ee_2$ : end of  $ee_2$ -sucking,in  $e_2$ -result state fox  $a_1$  feels full

||

 $t_2 = \vartheta_{w_0} e_2$ :  $e_2$ -time

||

 ${}^T t'_2 = \vartheta_{w_0} RS_{w_0} e_2$ :  $e_2$ -result.time

1.2<sup>3</sup> ...and then

tánon'

and

[eel <sup>1</sup>ee  $\subseteq_{d\Omega}$  RS dε];*if*<sub>3</sub>

...took a little bit for a snack.

stónha

*little.bit*<sup>P</sup>[| dεε ∈ dη<sup>εε</sup>]; [bl b =<sub>dΩ</sub> dκ<sup>β</sup>{RS<sup>f</sup>dεε}, *small*{b, (dκ<sup>β</sup>| RS<sup>f</sup>dη<sup>εε</sup>)}];*ib*<sub>3</sub>

y-

on.s.a-

XX-

"EE- (s-)

IND- (wa'-)

*mf*<sub>3</sub>[ $\mathcal{E}$  |  $\mathcal{E} =_{d\Omega} {}^f d\epsilon\epsilon$ ]; [ $\mathcal{E}\mathcal{E}$  | dε = <sup>1</sup>εε]; [|  $\mathfrak{V}_{d\Omega} {}^1 d\epsilon\epsilon < \mathfrak{V}_{d\omega} d\epsilon$ ];

ha-

3sm-

[| 3sm<sub>dΩ</sub> dα]; [| AG dεε = dα]

(a)t-

-énna't-

se-

-snack.on-

[| AG dεε = DA {RS dεε}]; [| <sup>f</sup>dεε: AG *snack.on* dβ]; <sup>1</sup>[| *process* dεε]

-e'

-EVT

[| <sup>1</sup>dεε  $\subseteq_{d\Omega}$  dτ]; [tl t =<sub>dΩ</sub>  $\mathfrak{V}$ RS <sup>1</sup>dεε] $w_0 \in {}^\top p_0$ 

⋮

====...

1

••...•••

2

•

||

3

••

•

||

 $(p_0$ -story worlds)

⋮

 $s'_1 = \text{RS}_{w_0} e'_1$ :  $k^{\alpha}_1$ -mare is still lying in  $l_1$  $k^{\alpha}_1$ -mare is asleep $ee_2$ : fox  $a_1$   $h^{\epsilon\epsilon}_2$ -sucks  $k^{\beta}_2$ -milk from  $k^{\alpha}_1$ -mare $e_2 = {}^f ee_2$ : end of  $ee_2$ -sucking,in  $e_2$ -result state fox  $a_1$  feels full $t_2 = \mathfrak{V}_{w_0} e_2$ :  $e_2$ -time $t'_2 = \mathfrak{V}_{w_0} \text{RS}_{w_0} e_2$ :  $e_2$ -result.time $ee'_2$ : fox  $a_1$  again  $h^{\epsilon\epsilon}_2$ -sucks  $k^{\beta}_2$ -mlk fr  $k^{\alpha}_1$ -mare ${}^f ee'_2 = [{}^1 \mathcal{E}\mathcal{E}_2]w_0$ : end of  $ee'_2$ -sucking, resultingin  $b_2$ -small amt (small for rs of  $h^{\epsilon\epsilon}_2$ -sucking)of  $k^{\beta}_2$ -milk, 1st stage of  $\mathcal{E}\mathcal{E}_2$ -action plan ${}^\top t''_2 = \mathfrak{V}_{w_0} [{}^1 \mathcal{E}\mathcal{E}_2]w_0$ : result tm of 1st stg of  $\mathcal{E}\mathcal{E}_2$  $w_2 \in \text{Dom } {}^f \mathcal{E}\mathcal{E}_2$ 

•...•

 $(\mathcal{E}\mathcal{E}_2$ -action plan successfully completed) $\langle [{}^1 \mathcal{E}\mathcal{E}_2]w_0, \dots, \langle [{}^f \mathcal{E}\mathcal{E}_2]w_2 \rangle$ :activity by fox  $a_1$ , ending with fox  $a_1$ snacking on  $b_2$ -milk sucked out in  $\mathcal{E}_2$

1.3<sup>1</sup> He had just gone a short distance, when...

kwah ken if  
*just* some  
 $P[| \mathbf{d}\tau =_{\mathbf{d}\Omega} \vartheta \text{RS } ^1 d\exists\exists]; [ee| ee =_{\mathbf{d}\Omega} \langle ^2 d\exists\exists, ^3 d\exists\exists \rangle]; [t| \mathbf{t} =_{\mathbf{d}\Omega} \vartheta \text{RS } ^1 d\epsilon\epsilon]; [e| e \in d\epsilon\epsilon];$   
 ni- yó-  
*of-* 3s<sub>U</sub>-  
 $[k^\pi | d\exists\exists: k^\pi\{\epsilon\} = \Pi\{\epsilon\}]; P[| 3s d\pi]; [ | dk^\pi\{^1 d\exists\exists\} =_{\mathbf{d}\Omega} d\pi];$   
 re- -a'  
*distance-* -DIM  
 $[ | ^1 d\exists\exists <_{\mathbf{d}\Omega} d\epsilon]; P[ | d\epsilon =_{\mathbf{d}\Omega} ^3 d\exists\exists]; [ | \mathbf{l} =_{\mathbf{d}\Omega} dk^\pi\{d\epsilon\}];$   
 n- ye- s-  
*of-* XX- "EE-  
 $[ | dk^\pi\{d\epsilon\} =_{\mathbf{d}\Omega} \mathbf{d}\pi]; [ | d\epsilon = ^f d\epsilon\epsilon]; [ | d\epsilon\epsilon =_{\mathbf{d}\Omega} \langle ^2 d\exists\exists, ^3 d\exists\exists \rangle];$   
 haw-  
 3sm-  
 $[ | 3sm_{\mathbf{d}\Omega} \mathbf{d}\alpha]; [ | \text{AG } d\epsilon\epsilon = \mathbf{d}\alpha];$   
 e-  
 go-  
 $[ | d\epsilon\epsilon: \text{AG } go.along_{\mathbf{d}\Omega} dk^\pi];$   
 -non  
 -STA  
 $[s| s =_{\mathbf{d}\Omega} \text{RS } ^1 d\epsilon\epsilon]; [ | \mathbf{d}\tau \subseteq_{\mathbf{d}\Omega} d\sigma];$

-----  
 $w_0 \in {}^\top p_0$   
 $\vdots$

( $p_0$ -story worlds)  
 $\vdots$

•

${}^f ee'_2 = [{}^1 \mathcal{E}\mathcal{E}_2]w_0$ : end of  $ee'_2$ -sucking, resulting  
 in  $b_2$ -small amt (small for rs of  $h^{\epsilon\epsilon}_2$ -sucking)  
 of  $k^b$ -milk, 1st stage of  $\mathcal{E}\mathcal{E}_2$ -action plan

||

$t''_2 = \vartheta_{w_0} [{}^1 \mathcal{E}\mathcal{E}_2]w_0$ : result tm of 1st stg of  $\mathcal{E}\mathcal{E}_2$

••

$ee_3 = \langle [{}^2 \mathcal{E}\mathcal{E}_2]w_0, [{}^3 \mathcal{E}\mathcal{E}_2]w_0 \rangle$ : nxt 2 stgs of  $\mathcal{E}\mathcal{E}_2$ ,  
 fox  $a_1$  goes (away from  $l_1$ ) along path  $k^\pi_3$   
 just a little bit (compared to planned  ${}^f \mathcal{E}\mathcal{E}_2$ )

||

${}^\top t_3 = \vartheta_{w_0} \text{RS}_{w_0} {}^1 ee_3$ : aft. 1st stg of  $ee_3$ -short walk  
 $e_3 = {}^f ee_3 = [{}^3 \mathcal{E}\mathcal{E}_2]w_0$ :  $ee_3$ -end, jst 3rd  $\mathcal{E}\mathcal{E}_2$ -stage  
 fox  $a_1$  arrives at  ${}^\top l_3 = k^\pi_3 w_0 e_3$

=

$s_3 = \text{RS}_{w_0} {}^1 ee_3$ : result state of 1st stage of  ${}^1 ee_3$

~~~~~  
 $w_2 \in \text{Dom } {}^f \mathcal{E}\mathcal{E}_2$

( $\mathcal{E}\mathcal{E}_2$ -action plan successfully completed)

•••••

$\langle [{}^1 \mathcal{E}\mathcal{E}_2]w_2, \langle [{}^2 \mathcal{E}\mathcal{E}_2]w_0, [{}^3 \mathcal{E}\mathcal{E}_2]w_0, \dots, \langle [{}^f \mathcal{E}\mathcal{E}_2]w_2 \rangle$ :  
 activity by fox  $a_1$ , ending with fox  $a_1$   
 snacking on  $b_2$ -milk sucked out in  $[{}^1 \mathcal{E}\mathcal{E}_2]w_2$

1.3<sup>2</sup> ...he bumped into a bear.

tho

ib

K

[ $\mathbf{k}^\alpha$  al  $a =_{d\Omega} \mathbf{k}^\alpha \{d\varepsilon\}$ ];

o-

-hkwári

sg-

-bear

[| *one*( $d\alpha$ ,  $\mathbf{d}\kappa^\alpha$ ); [| *bear*  $\mathbf{d}\kappa^\alpha$ ];

wa-

t-

mf

IND-

EE-

[|  $\vartheta_{d\Omega} d\varepsilon < \vartheta_{d\omega} \mathbf{d}\varepsilon$ ]; [*eel recip*<sub>dΩ</sub> *ee*]; [|  $d\varepsilon \in d\varepsilon\varepsilon$ ];

hy-

33m-

[|  $33m_{d\Omega} \{\mathbf{d}\alpha, d\alpha\}$ ]; [**A** | **A** =  $\{\mathbf{d}\alpha, d\alpha\}$ ]; [|  $\cup_{AG} d\varepsilon\varepsilon =_{d\Omega} \mathbf{d}\alpha t$ ];

ate-

-ra'-

se-

*bump.into-*[|  $d\varepsilon\varepsilon$ : AG $\{\varepsilon\} =_{d\Omega}$  DA $\{d\varepsilon\varepsilon(\varepsilon)\}$ ]; [| ( $d\varepsilon\varepsilon$ : AG *come.upon*<sub>dΩ</sub> DA), ( $d\varepsilon\varepsilon$ :  $\vartheta\varepsilon =_{d\Omega} \vartheta d\varepsilon\varepsilon(\varepsilon)$ )]

-ne'

-EVT

[|  $d\varepsilon\varepsilon \subseteq_{d\Omega} \mathbf{d}\tau$ ]; [| **t** | **t** =<sub>dΩ</sub>  $\vartheta_{RS} d\varepsilon\varepsilon$ ];reality  $\top w^*$ :

- $\top e^*$ : speech event
- |  $t^*$ :  $e^*$ -now

-----

 $w_0 \in \top p_0$   
 $\vdots$ 

( $p_0$ -story worlds)  
 $\vdots$

- ${}^f ee'_2$ : end of  $ee'_2$ -sucking, resulting in  $b_2$ -small amt (small for rs of  $h^{\varepsilon\varepsilon}_2$ -sucking) of  $k^b$ -milk
- ||  $t''_2 = \vartheta_{w_0} {}^f ee'_2$ : result tm of  $ee'_2$ -sucking
- $ee_3$ : fox  $a_1$  goes (away from  $l_1$ ) along path  $k^\pi_3$  just a little bit (compared to  $\mathcal{E}\mathcal{E}_2$ -plan)
- ||  $t_3 = \vartheta_{w_0} RS_{w_0} {}^1 ee_3$ : aft. 1st stg of  $ee_3$ -short walk
- $e_3 = {}^f ee_3 = [{}^3 \mathcal{E}\mathcal{E}_2]w_0$ :  $ee_3$ -end, jst 3rd  $\mathcal{E}\mathcal{E}_2$ -stage fox  $a_1$  arrives at  $\top l_3 = k^\pi_3 w_0 e_3$
- =  $s_3 = RS_{w_0} {}^1 ee_3$ : result state of 1st stage of  ${}^1 ee_3$
- $ee'_3 = \{\langle e_3, ee'_3(e_3) \rangle, \langle ee'_3(e_3), e_3 \rangle\}$
- || fox  $a_1$  and  $k^\alpha_3$ -bear  $a_3$  come upon each other
- ||  $\top t'_3 = \vartheta_{w_0} ee'_3$ :  $ee'_3$ -meeting result time

1.4<sup>1</sup> The bear said:

wa-  
 IND-  
 [el ]; [l  $\vartheta_{d\Omega} d\epsilon < \vartheta_{d\omega} \mathbf{d}\epsilon$ ];  
  
 hèn-  
 3sm-  
 [l  $3sm_{d\Omega} \mathbf{d}\kappa^\alpha\{d\epsilon\}$ ]; [l AG  $d\epsilon =_{d\Omega} \mathbf{d}\kappa^\alpha\{d\epsilon\}$ ];  
  
 -ron-  
 -say  
 [l  $d\epsilon$ : AG  $speak_{d\Omega}$ ];  
 -'  
 -EVT  
 [l  $d\epsilon \subseteq_{d\Omega} \mathbf{d}\tau$ ]; [tl  $t =_{d\Omega} \vartheta_{RS} d\epsilon$ ];  
  
 n=  
 D<sub>T</sub>  
 [l  $d\alpha =_{d\Omega} \mathbf{d}\kappa^\alpha\{d\epsilon\}$ ];  
  
 o-                    -hkwári  
 sg-                    -bear  
 [l  $one(d\alpha, \mathbf{d}\kappa^\alpha)$ ]; [l  $bear \mathbf{d}\kappa^\alpha$ ];

mf

ff

$w_0 \in {}^\top p_0$   
 $\vdots$

( $p_0$ -story worlds)

•  
 ||  
 ••  
 $\vdots$   
 :  
 ||  
 •  
 ||

$\vdots$   
 ${}^f ee'_2$ : end of  $ee'_2$ -sucking, resulting in  $b_2$ -small  
 amt (small for rs of  $h^{e_2}$ -sucking) of  $k^\beta$ -milk  
 $t''_2 = \vartheta_{w_0} {}^f ee'_2$ : result tm of  $ee'_2$ -sucking  
 $ee_3$ : fox  $a_1$  goes (away from  $l_1$ ) along path  $k^\pi_3$   
 just a little bit (compared to  $\mathcal{E}\mathcal{E}_2$ -plan)  
 $\vdots$   
 $ee'_3 = \{\langle e_3, ee'_3(e_3) \rangle, \langle ee'_3(e_3), e_3 \rangle\}$   
 fox  $a_1$  and  $k^\alpha_3$ -bear  $a_3$  come upon each other  
 $t'_3 = \vartheta_{w_0} ee'_3$ :  $ee'_3$ -meeting result time  
 $e_4$ :  $k^\alpha_3$ -bear  $a_3$  speaks  
 ${}^\top t_4 = \vartheta_{w_0} RS e_4$ :  $e_4$ -result time

1.4<sup>2</sup> “ (shift to bear’s voice)[el e = dε]; [tl t =<sub>dΩ</sub> θdε];

(oh or begin question intonation)

WH

[ℰ | (dε: AG *request*<sub>dΩ</sub> ℰ), (ℰ: AG *specify* OB)]; <sup>I</sup>[ | AG d∃ = DA dε];

what...

n= -ah -òt.en *if*D<sub>τ</sub>= -thing -kind.CL[k<sup>β</sup> | k<sup>β</sup> =<sub>dΩ</sub> OB d∃]; [ | inanimate dk<sup>β</sup>]; [ | dΩ ⊆ Dom dk<sup>β</sup>];

...is that...

ne’ thiken *ib*D<sub>τ</sub> that[b | b =<sub>dΩ</sub> dk<sup>β</sup>{dε}]; [ | dε: AG *point.at*<sub>dΩ</sub> dβ];

...stuff bulging in your cheeks

sa- *mf*2s<sub>U</sub>-[ | 2s<sub>dΩ</sub> dα]; [s | DA s =<sub>dΩ</sub> dα];

-hnoskw-

-a-

-hnont-

*cheek.cavity-*

-n/v-

*-have.full.cheeks-*[k<sup>π</sup> | k<sup>π</sup> *cheek.cavity.of* DA]; <sup>P</sup>[ | dk<sup>π</sup> *cheek.cavity.of* DA]; [ | dσ: dβ *fill*<sub>dΩ</sub> dk<sup>π</sup>];

-e’

-STA

[ | dτ ⊆<sub>dΩ</sub> dσ];

? (end of question intonation)

” (end bear’s voice)

[ | d∃ ⊆ θRS dε]; [tl t =<sub>dΩ</sub> θRS dε]; [el e = dε<sub>1</sub>]w<sub>0</sub> ∈ <sup>τ</sup>p<sub>0</sub>  
⋮(p<sub>0</sub>-story worlds)ee’<sub>3</sub> = {⟨e<sub>3</sub>, ee’<sub>3</sub>(e<sub>3</sub>)⟩, ⟨ee’<sub>3</sub>(e<sub>3</sub>), e<sub>3</sub>⟩}fox a<sub>1</sub> and k<sup>α</sup><sub>3</sub>-bear a<sub>3</sub> come upon each othert’<sub>3</sub> = θ<sub>w<sub>0</sub></sub> ee’<sub>3</sub>: ee’<sub>3</sub>-meeting result time<sup>(τ)</sup>e<sub>4</sub>: k<sup>α</sup><sub>3</sub>-bear a<sub>3</sub> speaks, requesting ℰ<sub>4</sub>-answert<sub>4</sub> = θ<sub>w<sub>0</sub></sub> RS e<sub>4</sub>: e<sub>4</sub>-result timet’<sub>4</sub> = θ<sub>w<sub>0</sub></sub> e<sub>4</sub>: e<sub>4</sub>-request times<sub>4</sub>: e<sub>4</sub>-dat has his cheeks full of <sup>τ</sup>k<sup>β</sup><sub>4</sub>-stuff b<sub>4</sub><sup>τ</sup>t’’<sub>4</sub> = θ<sub>w<sub>0</sub></sub> RS e<sub>4</sub>: e<sub>4</sub>-request result timew<sub>4</sub> ∈ Dom ℰ<sub>4</sub>(e<sub>4</sub>-requested worlds)<sup>τ</sup>t’’<sub>4</sub> = θ<sub>w<sub>4</sub></sub> RS e<sub>4</sub>: e<sub>4</sub>-request result time<sup>τ</sup>ℰ<sub>4</sub>w<sub>4</sub>: e<sub>4</sub>-requested ans, e<sub>4</sub>-dat specifies <sup>τ</sup>k<sup>β</sup><sub>4</sub>

1.5<sup>1</sup> The fox said:

wa-  
 IND-  
 [el]; [l  $\vartheta_{d\Omega} d\epsilon < \vartheta_{d\omega} \mathbf{d}\epsilon$ ];  
 hèn-  
 3sm-  
 [l  $3sm_{d\Omega} \mathbf{d}\alpha$ ]; [l AG  $d\epsilon =_{d\Omega} \mathbf{d}\alpha$ ];  
 -ron-  
 -say-  
 [pl  $d\epsilon$ : AG  $say_{d\Omega} p$ ]; [l  $d\epsilon =_{d\Omega} \mathbf{d}\exists$ ];  
 -'  
 -EVT  
 [l  $d\epsilon \subseteq_{d\Omega} \mathbf{d}\tau$ ]; [tl  $t =_{d\Omega} \vartheta RS d\epsilon$ ];  
 ne                      tsitsho  
 D<sub>T</sub>                      fox  
 [l  $\mathbf{d}\alpha =_{d\Omega} d\kappa^\alpha\{d\epsilon\}$ ]; [l fox  $d\kappa^\alpha$ ]

mf

ff

-----  
 $w_0 \in {}^T p_0$   
 $\vdots$

 $(p_0$ -story worlds)

:

 $ee'_3 = \{\langle e_3, ee'_3(e_3) \rangle, \langle ee'_3(e_3), e_3 \rangle\}$ fox  $a_1$  and  $k^\alpha_3$ -bear  $a_3$  come upon each other

||

 $t'_3 = \vartheta_{w_0} ee'_3$ :  $ee'_3$ -meeting result time

•

 $e_4$ :  $k^\alpha_3$ -bear  $a_3$  speaks, requesting  $\mathcal{E}_4$ -answer

||

 $t_4 = \vartheta_{w_0} RS e_4$ :  $e_4$ -result time

||

 $t'_4 = \vartheta_{w_0} e_4$ :  $e_4$ -request time

...=...

 $s_4$ :  $e_4$ -dat has his cheeks full of  ${}^T k^\beta_4$ -stuff  $b_4$ 

||

 $t''_4 = \vartheta_{w_0} RS e_4$ :  $e_4$ -request result time

•

 $e_5 = {}^T \mathcal{E}_4 w_0$ :  $e_4$ -requested answer, fox  $a_1$ specifies  ${}^T k^\beta_4$ , by claiming to be in  $p_5$ 

||

 ${}^T t_5 = \vartheta_{w_0} RS_{w_0} e_5$ :  $e_5$ -answer result time

~~~~~  
 $w_4 \in \text{Dom } \mathcal{E}_4$

 $(e_4$ -requested worlds)

||

 ${}^T t''_4 = \vartheta_{w_4} RS e_4$ :  $e_4$ -request result time

•

 ${}^T \mathcal{E}_4 w_4$ :  $e_4$ -requested ans,  $e_4$ -dat specifies  ${}^T k^\beta_4$ 

~~~~~  
 $w_5 \in p_5$

 $(e_5$ -claim worlds)

1.5<sup>2</sup> “ (shift to fox’s voice)[el e = dε]; [tl t =<sub>dΩ</sub> θdε]; [p<sub>ω</sub> p<sub>ω</sub> = λ<sub>w</sub> ∈ dΩ.dΩ];

[There is] a mare...

ko-

if: if

3s.3s-

P[h<sup>ε</sup> 3s AG{dη<sup>ε</sup>}, 3s DA{dη<sup>ε</sup>}); [k<sup>α</sup> DA{dη<sup>ε</sup>} = k<sup>α</sup>{dη<sup>ε</sup>}];

hsaten-

-s

*ride astride*

-DUR

[l dη<sup>ε</sup>: AG *ride astride* DA]; [l dt ⊆<sub>dΩ</sub> dη<sup>ε</sup>];

...over there...

ise-

if: ib

*there-*[sl dε: AG *point.to*<sub>dΩ</sub> s]; [l dα<sub>1</sub> =<sub>dωΩ</sub> dk<sup>α</sup>{dσ}]; [a l a = dα<sub>1</sub>];

-nekwa

*-direction*[ll Πdσ ⊆<sub>dωΩ</sub> <sup>1</sup>ll, Πdε ⊆<sub>dΩ</sub> <sup>f</sup>ll];

...sleeping, ...

k-

if: mf

XX-

[l dσ ⊆<sub>dωΩ</sub> <sup>1</sup>dππ];

yó-

3sf<sub>U</sub>-P[l 3sf<sub>dωΩ</sub> dk<sup>α</sup>{dσ}]; [l DA dσ =<sub>dωΩ</sub> dk<sup>α</sup>{dσ}];

-tá’-

-s

*-sleep-*

-DUR

[l dσ: DA *sleep*<sub>dωΩ</sub>]; [l dt ⊆<sub>dωΩ</sub> dσ];1.5<sup>3</sup> I have sucked milk from her.

mf

y-

a’-

XX-

IND-

[eel dσ<sub>1</sub> =<sub>dωΩ</sub> RS <sup>f</sup>ee]; [el e = <sup>f</sup>dεε]; P[l θ<sub>dωΩ</sub> dε < θ<sub>dΩ</sub> dε];

ke-

1s.3s-

P[l 1s dα, 3s dα]; [l AG dε =<sub>dωΩ</sub> dα, DA dε =<sub>dωΩ</sub> dα];

non’-

ké:ra-

*milk.of-**drink.from-*[l dk<sup>β</sup> *milk.of* dk<sup>α</sup>]; [h<sup>εε</sup> h<sup>εε</sup>: AG *drink* dk<sup>β</sup> *from* dk<sup>α</sup>]; [l dεε ∈<sub>dωΩ</sub> dη<sup>εε</sup>];

-‘

-EVT

P[l dε = <sup>f</sup>dεε]; [l dt ⊆<sub>dωΩ</sub> RS dε]; [tl t =<sub>dωΩ</sub> θRS dε]

|                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
|--------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_0 \in {}^\top p_0$<br>$\vdots$<br>$\vdots$<br>$\bullet$<br>$\text{====}\dots$<br>$\parallel$<br>$\bullet$<br>$\parallel$<br>$ $               | <p>(<math>p_0</math>-story worlds)</p> $\vdots$<br>$e_4$ : bear $a_3$ asks fox $a_1$ for $\mathcal{E}_4$ -ans ('what's $k_4^\beta$ ?')<br>$\vdots$<br>$s_4$ : $e_4$ -dat (fox $a_1$ ) has cheeks full of ${}^\top k_4^\beta$ -stuff $b_4$<br>$t''_4 = \mathfrak{D}_{w_0} \text{RS } e_4$ : $e_4$ -request result time<br>${}^\top e_5 = {}^\top \mathcal{E}_4 w_0$ : $e_4$ -requested answer,<br>fox $a_1$ specifies ${}^\top k_4^\beta$ by claiming to be in $p_5$<br>$t_5 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_5$ : $e_5$ -answer result time<br>$t'_5 = \mathfrak{D}_{w_0} e_5$ : $e_5$ -answer now |
| ~~~~~                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| $w_5 \in p_5 = \text{Ran } {}^\top p_{w_5}$<br>$\dots\text{====}\dots$<br>$\bullet\bullet\bullet$<br>$\text{====}\dots$<br>$\text{       }\dots$ | <p>(<math>e_5</math>-claim worlds)</p> $s_5$ : ${}^\top k_5^\alpha$ -mare $a_2$ sleeps at beg of $l_5$ -path (pointed at by ${}^\top e_5$ -agt = fox $a_1$ ), leading to ${}^\top e_5$ -here<br>$ee_5$ : ${}^\top e_5$ -agt (fox $a_1$ ) $h^{\varepsilon\varepsilon}_5$ -sucks ${}^\top k_4^\beta$ -milk from ${}^\top k_5^\alpha$ -mare $a_2$<br>$s_4 = \text{RS}_{w_5} {}^f ee_5$ : fox $a_1$ has cheeks full of ${}^\top k_4^\beta$ -milk<br>${}^\top t''_5 = \text{RS}_{w_5} {}^f ee_5$ : $ee_5$ -sucking result time                                                                                |

1.5<sup>f</sup> ” (end fox’s voice)  
[el e = dε<sub>1</sub>];

1.6 “owá” wa-hèn-ron-‘ ki o-hkwári.  
Gosh! IND-3sm-say-EVT N sg-bear  
“Gosh!” said the bear.

“ká-ti’ en-ske-natón-ha-hs-e’  
“wh-how HYP-2s.1s-show-go.to-for-EVT  
“How about showing me...

ka’-nón ni-yó-ta’-s  
wh-place/time of-3sf<sub>U</sub>-sleep-DUR  
...where she’s sleeping,...

aón-to n=í’i a-ke-non’-kéra-‘ óni  
OPT.3s<sub>U</sub>-be.possible.STA D<sub>T</sub>=me OPT-1s.3s-milk-suck-EVT also  
...[then] I could suck milk from her too.”

## Formalization (2): Non-indicative Mohawk discourse online

### 1. KEY PLAYERS FOR REFERENCE TO EXPECTATIONS AND/OR DESIRES:

**Form**            **MB gloss (stands for)**    **1st ex**    **Presuppositional test (<sup>P</sup>); update; implicature (<sup>I</sup>)**

**V-slot 1 (opt): CATEGORY-NEUTRAL prefix:**

|            |                        |      |                                                                                             |
|------------|------------------------|------|---------------------------------------------------------------------------------------------|
| <i>n-</i>  | <i>of</i>              | §1.1 | $[e  d\kappa^{\pi}\{e\} =_{d\Omega} d\pi]$                                                  |
|            |                        | §1.3 | $[k^{\pi}  d\varepsilon\varepsilon: k^{\pi}\{\varepsilon\} =_{d\Omega} \Pi\{\varepsilon\}]$ |
| <i>sh-</i> | <i>wth</i> ('with')    | §4.3 |                                                                                             |
| <i>th-</i> | <i>w/o</i> ('without') | §2.6 |                                                                                             |

**Slot 2 (finite V): MOOD inflection = (CL<sub>M</sub><sup>\*</sup>) + MOOD + (CL<sub>M</sub>)**

|               |                           |                   |                                                                                                          |      |                                                                                                    |
|---------------|---------------------------|-------------------|----------------------------------------------------------------------------------------------------------|------|----------------------------------------------------------------------------------------------------|
| <i>t(e)-</i>  | EE (pl event)             | §1.1              | $[eel\ prc_{d\Omega}\ ee]$                                                                               | §1.3 | $[eel\ rcp_{d\Omega}\ ee]$                                                                         |
| <i>(t)s-</i>  | "EE (part of pl event)    | §1.2 <sup>3</sup> | $[\mathcal{E}\mathcal{E}  d\exists = {}^1\mathcal{E}\mathcal{E}]$                                        | §1.3 | $[  d\varepsilon\varepsilon =_{d\Omega} \langle {}^2d\exists\exists, {}^3d\exists\exists \rangle]$ |
| <i>y(e)-</i>  | XX (end of chain)         | §1.1              | $[  d\varepsilon = {}^f d\varepsilon\varepsilon]$                                                        | §2.1 | $[\mathcal{E}\mathcal{E}\ \mathcal{A} \ ^f\mathcal{E}\mathcal{E} \subseteq \mathcal{L}]$           |
| <i>t(e)-</i>  | XX (beg. of chain)        | §1.5              | $[s  s \subseteq_{d\Omega} {}^1d\pi\pi]$                                                                 |      |                                                                                                    |
| <i>wa'-</i>   | IND (indicative)          | §1.1              | $[  \vartheta_{d\Omega} d\varepsilon < \vartheta_{d\omega} d\varepsilon]$                                |      | (realized <i>event</i> )                                                                           |
|               |                           | §1.2 <sup>1</sup> | $[  \vartheta_{d\Omega} {}^1d\varepsilon\varepsilon < \vartheta_{d\omega} d\varepsilon]$                 |      | (realized <i>1st</i> of <i>event-chain</i> )                                                       |
|               |                           | §1.2 <sup>3</sup> | $[  \vartheta_{d\Omega} {}^1d\exists\exists < \vartheta_{d\omega} d\varepsilon];$                        |      | (realized <i>1st</i> of <i>planned ev's</i> )                                                      |
|               |                           | MB05              | $[  \vartheta_{d\Omega} {}^1d\eta^{\varepsilon} < \vartheta_{d\omega} d\varepsilon]$                     |      | (realized <i>1st</i> of <i>habitual ev's</i> )                                                     |
| <i>en-</i>    | <b>HYP (hypothetical)</b> | §1.6 <sup>2</sup> | $[\mathcal{I} \ \mathcal{I} =_{d\omega\Omega} \vartheta RS\ d\varepsilon];$                              |      | <sup>1</sup> [  RS d\varepsilon: DA <i>expect</i> <sub>d\Omega</sub> d\omega\Omega]                |
|               |                           | §2.1 <sup>4</sup> | $[  d\omega\tau =_{d\omega\Omega} \vartheta RS\ d\exists];$                                              |      | <sup>1</sup> [  RS d\exists: DA <i>expect</i> d\omega\Omega]                                       |
|               |                           | BT97              | $[\mathcal{D} \ \mathcal{D} =_{d\omega\Omega} \vartheta RS\ d\eta^{\varepsilon}];$                       |      | <sup>1</sup> [  RS d\eta^{\varepsilon}: DA <i>expect</i> d\omega\Omega]                            |
| <i>a(on)-</i> | <b>OPT (optative)</b>     | §2.1 <sup>3</sup> | $[  {}^1d\exists\exists \subseteq_{d\omega\Omega} \vartheta RS\ d\varepsilon];$                          |      | <sup>1</sup> [  RS d\varepsilon: DA <i>want</i> <sub>d\Omega</sub> d\exists\exists];               |
|               |                           | §1.6 <sup>4</sup> | $[\mathcal{E}\mathcal{E}  {}^1\mathcal{E}\mathcal{E} \subseteq_{d\omega\Omega} \vartheta RS\ d\exists];$ |      | <sup>1</sup> [  RS d\exists: DA <i>want</i> d\exists\exists];                                      |
|               |                           | §1.6 <sup>3</sup> | $[p_{\omega} \ \mathcal{A} \ BG \ \mathcal{S} \subseteq_{p\omega} \vartheta RS\ d\exists];$              |      | <sup>1</sup> [  RS d\exists: DA <i>want</i> d\omega\sigma]                                         |
| <i>te-</i>    | IRR (irrealis)            | §2.6              |                                                                                                          |      |                                                                                                    |

**Slot 3: Pronominal AGR with S, O**

|       |      |                                                                                                                       |
|-------|------|-----------------------------------------------------------------------------------------------------------------------|
| 2s.1s | §1.6 | <sup>P</sup> [  2s d\alpha, 1s d\alpha]; [  AG d\varepsilon =_{d\Omega} d\alpha, DA d\varepsilon =_{d\Omega} d\alpha] |
|-------|------|-----------------------------------------------------------------------------------------------------------------------|

**Slot 4: V.BASE = ({*se, se.se*}) + (n + n/v +) v (+ v\v)**

|                    |                   |                   |                                                                                 |
|--------------------|-------------------|-------------------|---------------------------------------------------------------------------------|
| <i>at-</i>         | <i>se-</i>        | §1.1              | $[  AG d\varepsilon\varepsilon =_{d\Omega} DA \{RS\ d\varepsilon\varepsilon\}]$ |
| <i>-stikahwah-</i> | <i>-go.along-</i> | §1.1              | $[k^{\pi}  d\varepsilon\varepsilon: AG\ go.along_{d\Omega}\ k^{\pi}]$           |
| <i>-en, -on</i>    | <i>-be</i>        | §1.1              | $[s  DA\ s =_{d\Omega} AG\ d\varepsilon\varepsilon]$                            |
| <i>-hakie</i>      | <i>-prg</i>       | §1.1              | $[  d\sigma =_{d\Omega} RS\ {}^1d\varepsilon\varepsilon]$                       |
| <i>-(ha)k</i>      | <i>-itr</i>       | §2.1 <sup>4</sup> | $[  \vartheta d\omega\sigma \subseteq d\eta^{\varepsilon\varepsilon}]$          |
| ⋮                  | ⋮                 | ⋮                 | ⋮                                                                               |

**Slot 5: ASPECT inflection = ASPECT + (CL<sub>A</sub>) asp-adjustment; <sup>T</sup>\tau\omega-location; pre-fb <sup>T</sup>\tau-update**

|                   |                                       |                   |                                                            |                                                                            |                                                                                  |
|-------------------|---------------------------------------|-------------------|------------------------------------------------------------|----------------------------------------------------------------------------|----------------------------------------------------------------------------------|
| <i>-(e)', -ne</i> | EVT (eventive)                        | §1.1              | $([e  e =_{d\Omega} BG\ d\sigma];)$                        | $[  d\varepsilon \subseteq_{d\Omega} d\tau];$                              | $[t  t =_{d\Omega} \vartheta RS\ d\varepsilon]$                                  |
|                   |                                       | §2.1 <sup>4</sup> |                                                            | $[  d\omega\tau \subseteq_{d\omega\Omega} d\eta^{\varepsilon\varepsilon};$ | $[\mathcal{D} \ \mathcal{D} = \vartheta RS\ {}^1d\eta^{\varepsilon\varepsilon}]$ |
| <i>-(h)s, -ha</i> | DUR (durative)                        | §1.1              | $([s  s =_{d\Omega} RS\ d\varepsilon];)$                   | $[  d\tau \subseteq_{d\Omega} d\sigma];$                                   |                                                                                  |
| <i>-(en), -on</i> | STA (stative)                         | §1.1              | $([s  s =_{d\Omega} RS\ d\varepsilon];)$                   | $[  d\tau \subseteq_{d\Omega} d\sigma];$                                   |                                                                                  |
| <i>-s-kwe'</i>    | DUR. <sup>h</sup> PRF ('used to')     | BT98              | $[s  BG\ s =_{d\omega} BG\ RS\ {}^f d\eta^{\varepsilon}];$ | $[  d\tau \subseteq_{d\omega} d\sigma];$                                   |                                                                                  |
| <i>-en-hne'</i>   | STA. <sup>n</sup> PRF (nth res state) | BT98              | $[s  s =_{d\omega} RS\ {}^n d\varepsilon\varepsilon];$     | $[  d\tau \subseteq_{d\omega} d\sigma];$                                   |                                                                                  |

## 2. IROQUOIAN VERBAL INFLECTION: TENSE, MOOD, OR VERBAL (IN)DEFINITENESS?

- Three hypotheses:

|               | TENSE/MOOD<br><u>Lounsbury 1953</u> | MOOD<br><u>Chafe '67, '70, Foster '86, MB '05</u> | VERBAL (IN)DEFINITENESS<br><u>Baker &amp; Travis 1997, 1998</u> |
|---------------|-------------------------------------|---------------------------------------------------|-----------------------------------------------------------------|
| <i>wa'</i> -  | past tense (PST)                    | indicative mood, <b>realized (1st) evt</b>        | ~ <i>a certain</i> (evt), *binding                              |
| <i>te'</i> -  | n.a.                                | neg mood (Chafe 70), <b>unrealized</b>            | n.a.                                                            |
| <i>en-</i>    | future tense (FUT)                  | future mood, <b>expectation</b>                   | ~ <i>a</i> (evt), bnd by FUT, GNR..                             |
| <i>a(on)-</i> | inf/subj/pol. req.                  | optative mood, <b>desire</b>                      | ~ <i>any</i> (evt), bnd by <i>want</i> ...                      |

## 3. INDICATIVE MOOD (review)

|              |                  |                   |                                                                                |                                                |
|--------------|------------------|-------------------|--------------------------------------------------------------------------------|------------------------------------------------|
| <i>wa'</i> - | IND (indicative) | §1.1              | $[ \vartheta_{d\Omega} d\epsilon < \vartheta_{d\omega} d\epsilon]$             | (realized <i>event</i> )                       |
|              |                  | (1)               | $[ \vartheta_{d\Omega} {}^1d\epsilon\epsilon < \vartheta_{d\omega} d\epsilon]$ | (realized <i>1st</i> of <i>event-chain</i> )   |
|              |                  | §1.2 <sup>3</sup> | $[ \vartheta_{d\Omega} {}^1d\exists\exists < \vartheta_{d\omega} d\epsilon]$ ; | (realized <i>1st</i> of <i>planned ev's</i> )  |
|              |                  | (3)               | $[ \vartheta_{d\Omega} {}^1d\eta^e < \vartheta_{d\omega} d\epsilon]$           | (realized <i>1st</i> of <i>habitual ev's</i> ) |

- *wa'*-verbs may be **current** (cf. Lounsbury) and/or **habitual** (cf. B&T)

## (1) Current process:

|                      |                           |     |
|----------------------|---------------------------|-----|
| Ka' wa-hs-e-'        | Ka-nat-akon wa'-k-e-'     | B&T |
| where IND-2s-go-EVT? | sg-town-LOC IND-1s-go-EVT | MB  |
| Where are you going? | I'm going to town.        | B&T |
|                      | (Mohawk: B&T 1997:217)    |     |

## (2) Current result state:

|                                                                                           |                        |     |
|-------------------------------------------------------------------------------------------|------------------------|-----|
| Wa-hs-ken-'                                                                               | ken thi r-onkwe...?    | B&T |
| IND-2s.3sm-see-EVT                                                                        | Y/N that sg.m-person   | MB  |
| Do you see (MB: <i>have you noticed</i> ) that man [with the fur coat and the straw hat]? |                        | B&T |
|                                                                                           | (Mohawk: B&T 1997:217) |     |

## (3) Current habit (see also (4) and (6)):

|                                                                             |  |    |
|-----------------------------------------------------------------------------|--|----|
| <i>Oneidas don't tell stories in the spring time.</i>                       |  |    |
| Kwah kens ne' ok t-on.s.a-ka-nyey-a-hkw-e'                                  |  | KM |
| just HAB D <sub>T</sub> emp EE- <sup>n</sup> EE-IND-3s-snow-n/v-go.away-EVT |  | MB |
| As soon as the snow goes away,...                                           |  | KM |
| o-khna' ne' wa'-hron-at-kenhra't-e'                                         |  | KM |
| emp-then D <sub>T</sub> IND-333m-se-stop-EVT                                |  | MB |
| ...they stop.                                                               |  | KM |

(Oneida: Karin Michelson 1981, p. 36)

## 3. PROSPECTIVE MOODS

## • Basic idea

*en-* expectation based on *speech situation* (**dε**), *hypothetical eventuality* (*də*), or *habit* (*dη*)

*a(on)-* desire based on *speech situation* (**dε**), *hypothetical eventuality* (*də*), or *habit* (*dη*)

## • Formalization:

|               |                           |                         |                                                                                                                    |                                                                                                       |
|---------------|---------------------------|-------------------------|--------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------|
| <i>en-</i>    | <b>HYP</b> (hypothetical) | <b>§1.6<sup>2</sup></b> | $[\mathcal{I} \mathcal{I} =_{d\omega\Omega} \vartheta_{RS} \mathbf{d}\varepsilon];$                                | $^1[  \text{RS } \mathbf{d}\varepsilon: \text{DA } \textit{expect}_{d\Omega} \mathbf{d}\omega\Omega]$ |
|               |                           | <b>§2.1<sup>4</sup></b> | $[  \mathbf{d}\omega\tau =_{d\omega\Omega} \vartheta_{RS} \mathbf{d}\varepsilon];$                                 | $^1[  \text{RS } \mathbf{d}\varepsilon: \text{DA } \textit{expect } \mathbf{d}\omega\Omega]$          |
|               |                           | (4–6)                   | $[\mathcal{D} \mathcal{D} =_{d\omega\Omega} \vartheta_{RS} \mathbf{d}\eta^\varepsilon];$                           | $^1[  \text{RS } \mathbf{d}\eta^\varepsilon: \text{DA } \textit{expect } \mathbf{d}\omega\Omega]$     |
| <i>a(on)-</i> | <b>OPT</b> (optative)     | <b>§2.1<sup>3</sup></b> | $[  \mathbf{d}\varepsilon \subseteq_{d\omega\Omega} \vartheta_{RS} \mathbf{d}\varepsilon];$                        | $^1[  \text{RS } \mathbf{d}\varepsilon: \text{DA } \textit{want}_{d\Omega} \mathbf{d}\varepsilon];$   |
|               |                           | <b>§1.6<sup>4</sup></b> | $[\mathcal{E}\mathcal{E} \mathbf{d}\varepsilon \subseteq_{d\omega\Omega} \vartheta_{RS} \mathbf{d}\varepsilon];$   | $^1[  \text{RS } \mathbf{d}\varepsilon: \text{DA } \textit{want } \mathbf{d}\varepsilon];$            |
|               |                           | <b>§1.6<sup>3</sup></b> | $[\mathbf{p}_\omega \mathcal{A} \text{BG } \mathcal{S} \subseteq_{p\omega} \vartheta_{RS} \mathbf{d}\varepsilon];$ | $^1[  \text{RS } \mathbf{d}\varepsilon: \text{DA } \textit{want } \mathbf{d}\omega\sigma]$            |

## • Examples

From sample text ('The Bear and the Fox'):

[*The bear said: "What is that stuff bulging in your mouth?"*

*The fox answered: "There's a mare over there sleeping, I have sucked milk from her."]*

1.6<sup>1</sup> "owá" wa-hèn-ron-‘ ki o-hkwári.  
*Gosh!* IND-3sm-say-EVT N sg-bear  
 "Gosh!" said the bear.

1.6<sup>2</sup> "ká-ti' en-ske-natón-ha-hs-e' ka'-nón ni-yó-ta'-s  
 "wh-how HYP-2s.1s-show-go.to-dat-EVT wh-*placetime* of-3sf<sub>U</sub>-sleep-DUR  
 "How about showing me where she's sleeping,..."

1.6<sup>3</sup> aón-to  
 OPT.3s<sub>U</sub>-be.possible.STA  
 ...[then] it would be possible...

1.6<sup>4</sup> n=i'í a-k-non'-kéra-‘ óni  
 D<sub>T</sub>=me OPT-1s-milk-suck-EVT also  
 ...for me to suck [her] milk too."

[So the two of them turned around and went back to the place where the mare was sleeping. The bear rightaway set to and sucked milk until he was full. 2.1<sup>1</sup> The fox then said:]

2.1<sup>2</sup> "toka'-nónw-a yo-yáner-e'  
 maybe-placetime-CL 3s<sub>U</sub>-be.nice-STA  
 "It might be nice..."

2.1<sup>3</sup> ne y-aon-sa-yeteni-ya't-énhaw-e'  
 D<sub>T</sub> <sup>f</sup>EE-OPT-<sup>n</sup>EE-12-body-carry-EVT  
 ...to carry her off...

2.1<sup>4</sup> khná'a kyótkon n=é'e en-ionkeni-nahskwa-yen-t-ak-e'  
 then always D<sub>T</sub>=(s)he HYP-12<sub>U</sub>-animal.of-have-cause-itr-EVT  
 ...then for ever it would make her our [milking mare].

- (4) [*Oneídas don't tell stories in the spring time. As soon as the snow melts they stop...*]
- <sup>1</sup> tsi' ke-ks-a' k-ehyahr-e' KM  
 D<sub>⊥</sub> 1s-child-CL 1s-remember-STA MB  
 When I was a little girl, I remember... KM
- kens tsi's n-a'-k-at-shanoni-' KM  
**HAB** so of-IND-1s-se-be.happy-EVT MB  
 ...I used to be so glad KM
- <sup>2</sup> n=are' s-a-yo-hsr-a-t-e' KM  
 D<sub>⊥</sub>=again XX-IND-3s-winter-n/v-be.there-EVT MB  
 ...when winter came again. KM
- <sup>3</sup> Nen ki are' wi en-s-wak-athontek-e' KM  
 D<sub>⊥</sub> N again emp **HYP**-<sup>n</sup>EE-1s<sub>U</sub>-hear-EVT MB  
 Now yet again I would hear... MB
- <sup>4</sup> en-s-hrati-kar-a-ton-<sup>4</sup> hroti-kstenha-okonha KM  
**HYP**-<sup>n</sup>EE-333m-story-n/v-say-EVT pl.m-old-PL<sub>α</sub> MB  
 ...the elders tell stories. MB
- (Oneida: Karin Michelson 1981, p. 36–7)

- (5) [*Corn was very useful (DUR) for the Indians: it sustained (DUR) them throughout the year.*]
- <sup>1</sup> Ki:ken o-ká:r-a' ne B&T  
*this* sg-story-CL D<sub>⊥</sub> MB  
 This story is about... MB
- tsi ni-ye-yér-hah-kwe' a-k-sot-ha B&T  
 D<sub>⊥</sub> of-3sf-do-DUR-<sup>h</sup>PRF sg.f-1s-grandparent-CL MB  
 ...what my grandmother used to do... B&T
- <sup>2</sup> n=ó:nen en-ye-nenhst-ohare-' B&T  
 D<sub>⊥</sub>=time/place **HYP**-3sf-corn-clean-EVT MB  
 ...when she would clean the corn... B&T
- <sup>3</sup> tánon' en-ye-the'ser-ón:ni-' B&T  
*and* **HYP**-3sf-flour-make-EVT MB  
 ...and make the flour... B&T
- <sup>4</sup> ohén:ton' tsi ni-yó:-re-' B&T  
*before/in.front* D<sub>⊥</sub> of-3s<sub>U</sub>-distance-CL MB  
 ...until finally... MB
- ka-na'taro-khón:we en-ye-na'tar-ísa-' B&T  
*sg-bread-real* **HYP**-3sf-bread-finish-EVT MB  
 ...she would finish making real (Mohawk) bread. MB
- (Mohawk: data from KO, p. 174,  
 B&T = Baker & Travis 1997:219)

- (6) [*In the spring Grandma would get out her seed corn, put it in a container and give it to my brother, sister, and me, and...*]
- <sup>1</sup> en-yonkhi-hró:ri-’ MB  
**HYP-3sf.133-tell-EVT** MB  
 ...she would tell us: MB
- <sup>2</sup> “Kayé:ri tóka-ni’ wisk ni-ka-nénhst-ake y-en-sewa-sen-ht-e’  
*four maybe-? five of-pl-corn-NUM XX-HYP-222.3-fall-cause-EVT*  
 “[You are expected to] drop four or five kernels...  
 áhsen ni-wahsít-ake na’-te-kon-teron-’ “  
*three of-feet-NUM of-EE-333-stay-STA*  
 ...three feet apart.
- <sup>3</sup> E’ thó ki’ n-a’-kwá-yer-e’.  
 D<sub>T</sub> K N of-**IND-133-do-EVT**  
 [And] that was how we did it.
- <sup>4</sup> Wa-kwa-hahok-ta-nihon-’  
**IND-133-do.row-with-process-EVT**  
 We did row after row...  
 ra-k-sot-ha tanon’ a-k-sot-ha  
*sg.m-1s-grandparent-CL and sg.f-1s-grandparent-CL*  
 ...[while] Grandpa and Grandma...  
 ohná:ken’ t-á:-n-e-’ ta-hoti’-rhor-on-hatie-’  
*behind/after EE-IND-33-go-EVT EE-33.3-cover-be-prg-STA*  
 ...followed up behind, covering [the kernels with soil]...  
 tsi ni-yo-re-’ en-ya-kwá-hsa-’  
 D<sub>⊥</sub> of-3s-distance-CL **HYP-XX-133-finish-EVT**  
 ...until we finished [the job]. (Mohawk: data from KO, p. 175)

- Subcategorized {HYP, OPT}: Implicated attitudes {*expected, desired*} cancelled?

- (7) -rharatsten- {OPT, HYP, \*IND} ‘promise (to)’  
 -á:ton’ {OPT, HYP, \*IND} ‘be possible (to)’  
 -kwéni {OPT, \*HYP, \*IND} ‘be able (to)’  
 -ehr {OPT, \*HYP, \*IND} ‘want (to)’  
 -on’wéskwani {OPT, \*HYP, \*IND} ‘like (to)’

## APPENDIX: PROSPECTIVE MOODS (HYP, OPT)

§1.6–1.9 *Fox finds food and shares it with Bear*

|                                                                                                                                                     |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
|-----------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_0 \in {}^T p_0$<br>$\vdots$<br>$\vdots$<br>$\bullet$<br>$\text{====...}$<br>$\parallel$<br>$\bullet$<br>$\parallel$<br>$ $                       | <p style="text-align: center;">(<math>p_0</math>-story worlds)</p> $\vdots$<br>$e_4$ : bear $a_3$ asks fox $a_1$ for $\mathcal{E}_4$ -ans ('what's $k_4^\beta$ ?')<br>$\vdots$<br>$s_4$ : $e_4$ -dat (fox $a_1$ ) has cheeks full of ${}^T k_4^\beta$ -stuff $b_4$<br>$t''_4 = \mathfrak{D}_{w_0} \text{RS } e_4$ : $e_4$ -request result time<br>$e_5 = {}^T \mathcal{E}_4 w_0$ : $e_4$ -requested answer,<br>fox $a_1$ specifies ${}^T k_4^\beta$ by claiming to be in $p_5$<br>$t_5 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_5$ : $e_5$ -answer result time<br>$t'_5 = \mathfrak{D}_{w_0} e_5$ : $e_5$ -answer now |
| $w_5 \in p_5 = \text{Ran } {}^T p_{w_5}$<br>$\dots \text{====} \dots$<br>$\bullet \bullet \bullet$<br>$\text{====} \dots$<br>$\text{       } \dots$ | <p style="text-align: center;">(<math>e_5</math>-claim worlds)</p> $s_5$ : ${}^T k_5^\alpha$ -mare $a_2$ sleeps at beg of $ll_5$ -path (pointed at by ${}^T e_5$ -agt = fox $a_1$ ), leading to ${}^T e_5$ -here<br>$ee_5$ : ${}^T e_5$ -agt (fox $a_1$ ) $h^{\varepsilon\varepsilon}$ -sucks ${}^T k_4^\beta$ -milk from ${}^T k_5^\alpha$ -mare $a_2$<br>$s_4 = \text{RS}_{w_5} {}^f ee_5$ : fox $a_1$ has cheeks full of ${}^T k_4^\beta$ -milk<br>${}^T t''_5 = \text{RS}_{w_5} {}^f ee_5$ : $ee_5$ -sucking result time                                                                                        |

1.6<sup>1</sup> “ (shift to bear’s voice)[el (e: AG *speak*<sub>dΩ</sub>), AG e =<sub>dΩ</sub> DA dε, DA e =<sub>dΩ</sub> AG dε]; [tl t =<sub>dΩ</sub> θdε];

Gosh!

owá!

*gosh* (admiring tone)[l dε: AG *exclaims.with.admiration* for<sub>dΩ</sub> DA];*if*

” (end bear’s voice)

[el e = dε<sub>1</sub>];

...said the bear.

wa-

IND-

[el e = dε<sub>1</sub>]; [l θ<sub>dΩ</sub> dε < θ<sub>dω</sub> dε];*mf*

hèn-

3sm-

<sup>P</sup>[l 3sm<sub>dΩ</sub> dα<sub>1</sub>]; [al a = dα<sub>1</sub>]; [l AG dε =<sub>dΩ</sub> dα];

-ron-

-’

-say-

-EVT

<sup>P</sup>[l dε: AG *speak*<sub>dΩ</sub>]; [l dε ⊆<sub>dΩ</sub> dτ]; [tl t =<sub>dΩ</sub> θRS dε];

ki’

o-hkwari

*ff*

N

sg-bear

[l dα =<sub>dΩ</sub> dκ<sup>α</sup><sub>1</sub>{dε}]; [k<sup>α</sup> k<sup>α</sup> = dκ<sup>α</sup><sub>1</sub>]; [l bear dκ<sup>α</sup>]



1.6<sup>2</sup> ...showing me...<sup>2</sup>

en-

mf

HYP-

[ $\mathcal{T}$ ]  $\mathcal{T} =_{\mathbf{d}\omega\Omega} \vartheta\text{RS } \mathbf{d}\varepsilon$ ; <sup>1</sup>[| RS  $\mathbf{d}\varepsilon$ : DA *expect*<sub>dΩ</sub>  $\mathbf{d}\omega\Omega$ ]

-ske

-2s.1s

[**a** al 2s<sub>dΩ</sub> **a**, 1s<sub>dΩ</sub> **a**]; [| AG{ $d\exists$ } =  $\mathbf{d}\alpha$ , DA{RS  $d\exists$ } =  $d\alpha$ ];

-natón

-show

[|  $d\exists$ : AG *show* DA  $d\pi$ ];

-ha

-hs-

-go.to

-dat-

[ $\mathcal{E}\mathcal{E}$ ] ( $\mathcal{E}\mathcal{E}$ : AG *go.along*  $d\pi\pi$ ),  $d\exists \subseteq \vartheta\text{RS } {}^f d\exists$ ]; [| DA{RS  $d\exists$ } =  $d\alpha$ ];

-e'

-EVT

[|  $d\exists \subseteq_{\mathbf{d}\omega\Omega} \mathbf{d}\omega\tau$ ]; [ $\mathcal{T}$ ]  $\mathcal{T} = \vartheta\text{RS } d\exists$ ];

... where...

ka'-

-nón

ff

wh-

-plc/tm

<sup>P</sup>[| ( $\mathbf{d}\varepsilon$ : AG *request*<sub>dΩ</sub>  $d\exists$ ),  $d\exists \subseteq \vartheta\text{RS } \mathbf{d}\varepsilon$ ]; [|  $d\exists \subseteq d\pi$ ];

...she's sleeping...

ni- -yó

of- -3sf<sub>U</sub><sup>P</sup>[|  $d\sigma \subseteq_{\mathbf{d}\Omega} d\pi$ ]; [| 3sf<sub>dΩ</sub>  $\mathbf{d}\kappa^\alpha\{d\sigma\}$ ]; [| DA  $d\sigma =_{\mathbf{d}\Omega} \mathbf{d}\kappa^\alpha\{d\sigma\}$ ];

-ta'

-sleep

<sup>P</sup>[|  $d\sigma$ : DA *sleep*<sub>dΩ</sub>];

-s

-DUR

[|  $\mathbf{d}\tau \subseteq_{\mathbf{d}\Omega} d\sigma$ ]

- 
- <sup>2</sup> • In any  $\mathbf{d}\omega\Omega$ -accessible world,  $\mathcal{T}$  is the time of the result state of  $\mathbf{d}\varepsilon$   
 $\mathcal{T} =_{\mathbf{d}\omega\Omega} \vartheta\text{RS } \mathbf{d}\varepsilon \quad := \quad \lambda i. \forall w \in \text{Dom } \mathbf{d}\omega\Omega_i \forall w' \in \mathbf{d}\omega\Omega_i w: \mathcal{T} w' = \vartheta_{w'} \text{RS}_{w'} \mathbf{d}\varepsilon_i$
- In  $\mathbf{d}\Omega$ , the experiencer of the result state of  $\mathbf{d}\varepsilon$  expects  $\mathbf{d}\omega\Omega$   
 $\text{RS } \mathbf{d}\varepsilon$ : DA *expect*<sub>dΩ</sub>  $\mathbf{d}\omega\Omega \quad := \quad \lambda i. \forall w \in \mathbf{d}\Omega_i \exists s: s = \text{RS}_w \mathbf{d}\varepsilon_i \wedge \text{expect}_w(s, \text{DA}_w s, \mathbf{d}\omega\Omega_i w)$
- Any realization of  $d\exists$  is an action whose agent shows the experiencer the place  $d\pi$   
 $d\exists$ : AG *show* DA  $d\pi \quad := \quad \lambda i. \forall w \in \text{Dom } d\exists \exists e: e = d\exists_w \wedge \text{show}_w(e, \text{AG}_w e, \text{DA}_w e, d\pi_i)$
- Any realization of  $\mathcal{E}\mathcal{E}$  is a walk along  $d\pi\pi$ -path  
 $\mathcal{E}\mathcal{E}$ : AG *go.along*  $d\pi\pi \quad := \quad \lambda i. \text{process } \mathcal{E}\mathcal{E}$   
 $\wedge \forall \mathcal{E} \in \mathcal{E}\mathcal{E} \forall w \in \text{Dom } \mathcal{E}: \text{walk}_w(\mathcal{E}w, \text{AG}_w \mathcal{E}w)$   
 $\wedge \forall \mathcal{E} \in \text{Dom } \mathcal{E}\mathcal{E} \forall w \in \text{Dom } \mathcal{E} \forall w' \in \text{Dom } \mathcal{E}\mathcal{E}(\mathcal{E}) \exists l \in \text{Dom } d\pi\pi:$   
 $l \subseteq \Pi_w \mathcal{E}w \wedge d\pi\pi_i(l) \subseteq \Pi_{w'} \mathcal{E}\mathcal{E}(\mathcal{E})w'$
- In any  $\mathbf{d}\omega\Omega$ -accessible world,  $d\exists$  is realized within  $\mathbf{d}\omega\tau$ -frame  
 $d\exists \subseteq_{\mathbf{d}\omega\Omega} \mathbf{d}\omega\tau \quad := \quad \lambda i. \forall w \in \text{Dom } \mathbf{d}\omega\Omega_i \forall w' \in \mathbf{d}\omega\Omega_i w: \vartheta_{w'} d\exists_w' \subseteq \mathbf{d}\omega\tau_i w'$

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|                                                                                                                                                                    |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_0 \in {}^\top p_0$<br>$\vdots$<br><ul style="list-style-type: none"> <li>•</li> <li> </li> <li>  </li> <li>•</li> <li>  </li> <li>•</li> </ul> <p>...===...</p> | <p>(<math>p_0</math>-story worlds)</p> $\vdots$<br>$e_5 = {}^\top \mathcal{E}_4 w_0$ : $e_4$ -requested answer,<br>fox $a_1$ specifies ${}^\top k_4^\beta$ by claiming to be in $p_5$<br>$t_5 = \mathfrak{D}_{w_0} e_5$ : $e_5$ -answer now<br>$t'_5 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_5$ : $e_5$ -answer result time<br>$e_6$ : bear $a_3$ exclaims with admiration for fox $a_1$<br>${}^\top t_6 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_6$ : $e_6$ -exclamation result time<br>${}^\top e'_6$ : bear $a_3$ requests & expects $\mathcal{E}_6$ dur RS $e'_6$<br>$s_5$ : ${}^\top k_5^\alpha$ -mare $a_2$ sleeps at beg $l_6$ of $ll_5$ -path |
| ~~~~~                                                                                                                                                              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| $w_6 \in \text{Dom } \mathcal{E}_6 = \text{Ran } {}^\top p_{\omega,6}$<br>       <br>••<br>•<br>                                                                   | <p>(<math>e'_6</math>-request/expectation of bear <math>a_3</math>)</p> $\mathcal{T}_6 w_6 = \mathfrak{D}_{w_6} \text{RS}_{w_6} e'_6$ : $e'_6$ -request result time<br>$\langle {}^1 \mathcal{E} \mathcal{E}_6 \dots {}^f \mathcal{E} \mathcal{E}_6 \rangle$ : fox $a_1$ & bear $a_3$ go along $ll_5$ -path<br>$\mathcal{E}_6 w_6$ : during ${}^f \mathcal{E} \mathcal{E}_6$ -result, fox $a_1$ shows bear $a_3$<br>bg $l_6$ of $ll_5$ -pth, plc of $s_5$ -sleep of ${}^\top k_5^\alpha$ -mare $a_2$<br>${}^\top \mathcal{T}'_6 w_6 = \mathfrak{D}_{w_6} \text{RS } \mathcal{E}_6 w_6$ : $\mathcal{E}_6$ -showing result time                      |
| ~~~~~                                                                                                                                                              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| $w_5 \in p_5 = \text{Ran } {}^\top p_{\omega,5}$<br>...===...<br>•••<br>====...<br>       ...                                                                      | <p>(<math>e_5</math>-claim by fox <math>a_1</math>)</p> $s_5$ : ${}^\top k_5^\alpha$ -mare $a_2$ sleeps at beg of $ll_5$ -path (pointed<br>at by ${}^\top e_5$ -agt = fox $a_1$ ), leading to ${}^\top e_5$ -here<br>$ee_5$ : ${}^\top e_5$ -agt (fox $a_1$ ) $h^{\text{ee}}_5$ -sucks ${}^\top k_4^\beta$ -milk from<br>${}^\top k_5^\alpha$ -mare $a_2$<br>$s_4 = \text{RS}_{w_5} {}^f ee_5$ : fox $a_1$ has cheeks full of ${}^\top k_4^\beta$ -milk<br>$t''_5 = \text{RS}_{w_5} {}^f ee_5$ : $ee_5$ -sucking result time                                                                                                                       |

1.6<sup>3</sup> ...then it would be possible...<sup>3</sup>

aon-  
 OPT-  
 $[\mathbf{p}_\omega \mathcal{A} \text{ BG } \mathcal{S} \subseteq_{\mathbf{p}_\omega} \vartheta \text{RS } d\exists]; {}^1[| \text{RS } d\exists: \text{DA } \textit{want } d\omega\sigma];$   
 - $\emptyset$   
 -3s<sub>U</sub>  
 $[| 3s \mathbf{d}\omega\Omega]; [| \text{Dom } d\omega\sigma =_{\mathbf{d}\omega\Omega} \mathbf{d}\omega\Omega];$   
 -to  
 -*be.possible*  
 $[| \textit{can}\{d\omega\sigma, \text{RS } d\exists\}];$   
 - $\emptyset$   
 -STA  
 $[| \mathbf{d}\omega\tau \subseteq_{\mathbf{d}\omega\Omega} d\omega\sigma];$

1.6<sup>4</sup> for me ...

n=  $\acute{i}'i$  *if*  
 D<sub>T</sub>= *me*  
 $[| \mathbf{d}\alpha =_{\mathbf{d}\Omega} \text{AG}\{d\epsilon\epsilon\}]; [\mathbf{a}| \text{AG}\{\mathbf{d}\epsilon\} =_{\mathbf{d}\Omega} \mathbf{a}];$

...to suck [her] milk too.

a- *mf*  
 OPT-  
 $[\mathcal{E}\mathcal{E} | \mathcal{E}\mathcal{E} \subseteq_{\mathbf{d}\omega\Omega} \vartheta \text{RS } d\exists]; {}^1[| \text{RS } d\exists: \text{DA } \textit{want } d\exists\exists];$   
 -ke  
 -1s  
 ${}^P[| 1s \mathbf{d}\alpha]; [| \text{AG } d\exists\exists =_{\mathbf{d}\omega\Omega} \mathbf{d}\alpha];$   
 -non'  $\text{-k\acute{e}ra-}$   
 -*milk.of*  $\text{-drink.from-}$   
 $[| \mathbf{d}\kappa^\beta \textit{milk.of } \mathbf{d}\kappa^\alpha]; {}^P[| d\eta^{\epsilon\epsilon}: \text{AG } \textit{drink } \mathbf{d}\kappa^\beta \textit{from } \mathbf{d}\kappa^\alpha]; [| d\exists\exists \in_{\mathbf{d}\omega\Omega} d\eta^{\epsilon\epsilon}]$   
 -'  
 -EVT  
 $[| {}^1d\exists\exists \subseteq_{\mathbf{d}\omega\Omega} \mathbf{d}\omega\tau]; [\mathcal{T}| \mathcal{T} = \vartheta \text{RS } {}^1d\exists\exists];$

$\acute{o}ni$  *ff*  
*also*  
 ${}^P[| \text{DA } \mathbf{d}\epsilon =_{\mathbf{d}\Omega} \text{AG}\{d\epsilon\epsilon\}, d\epsilon\epsilon \in_{\mathbf{d}\Omega} d\eta^{\epsilon\epsilon}];$

1.6<sup>f</sup> ” (end bear’s voice)

$[| \mathbf{e} = \mathbf{d}\epsilon_1];$

- 
- <sup>3</sup> • In any  $\mathbf{p}_\omega$ -accessible world, the beginning of  $\mathcal{S}$  is realized during the result state of the realization of  $d\exists$   
 $\text{BG } \mathcal{S} \subseteq_{\mathbf{p}_\omega} \vartheta \text{RS } d\exists \quad := \quad \lambda i. \forall w \in \text{Dom } \mathbf{p}_\omega \forall w' \in \mathbf{p}_\omega w: \vartheta_{w'} \text{BG}_{w'} \mathcal{S} w' \subseteq \vartheta_{w'} \text{RS}_{w'} d\exists_i w'$
- $d\omega\sigma$  is a possible realization of the result state of  $d\exists$   
 $\textit{can}\{d\omega\sigma, \text{RS } d\exists\} \quad := \quad \lambda i. \text{Dom } d\omega\sigma_i \subseteq \text{Dom } d\exists_i$   
 $\wedge \forall w \in \text{Dom } d\omega\sigma_i: d\omega\sigma_i w = \text{RS}_w d\exists_i w$

|                                                                                                                                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_0 \in {}^\top p_0$<br>$\vdots$<br><ul style="list-style-type: none"> <li>•</li> <li> </li> <li>  </li> <li>•</li> <li>  </li> <li>•</li> <li>...=====...</li> <li>•••</li> </ul>                                                                                                                                         | <p>(<math>p_0</math>-story worlds)</p> $\vdots$<br>$e_5 = {}^\top \mathcal{E}_4 w_0$ : $e_4$ -requested answer,<br>fox $a_1$ specifies ${}^\top k_4^\beta$ by claiming to be in $p_5$<br>$t_5 = \mathfrak{D}_{w_0} e_5$ : $e_5$ -answer now<br>$t'_5 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_5$ : $e_5$ -answer result time<br>$e_6$ : bear $a_3$ exclaims with admiration for fox $a_1$<br>${}^\top t_6 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_6$ : $e_6$ -exclamation result time<br>${}^\top e'_6$ : bear $a_3$ requests ${}^1$ (and expects) $\mathcal{E}_6$ dur RS $e'_6$<br>$s_5$ : ${}^\top k_5^\alpha$ -mare $a_2$ sleeps at beg $l_6$ of $ll_5$ -path<br>$ee_5$ : fox $a_1$ $h^{\text{ee}}_5$ -sucks ${}^\top k_4^\beta$ -milk frm ${}^\top k_5^\alpha$ -mare $a_2$                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| ~~~~~                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |
| $\mathcal{S}_6 = \langle \text{RS}_w \mathcal{E}_6 w : w \in \text{Ran } {}^\top p'_{\omega,6} \rangle$<br>$w'_6 \in \text{Dom } \mathcal{S}_6 = \text{Ran } {}^\top p'_{\omega,6}$<br><ul style="list-style-type: none"> <li>       </li> <li>••</li> <li>•</li> <li>     </li> <li>==</li> <li>•••</li> <li>  </li> </ul> | <p>(<math>\mathcal{E}_6</math>-result <math>p'_{\omega,6}</math>-desire of bear <math>a_3</math>)</p> $\mathcal{T}_6 w_6 = \mathfrak{D}_{w_6} \text{RS}_{w_6} e'_6$ : $e'_6$ -request result time<br>$\langle {}^1 \mathcal{E} \mathcal{E}_6 \dots {}^f \mathcal{E} \mathcal{E}_6 \rangle$ : fox $a_1$ & bear $a_3$ go along $ll_5$ -path<br>$\mathcal{E}_6 w_6$ : during ${}^f \mathcal{E} \mathcal{E}_6$ -result, fox $a_1$ shows bear $a_3$<br>bg $l_6$ of $ll_5$ -pth, plc of $s_5$ -sleep of ${}^\top k_5^\alpha$ -mare $a_2$<br>$\mathcal{T}'_6 w_6 = \mathfrak{D}_{w_6} \text{RS}_{w_6} \mathcal{E}_6 w_6$ : $\mathcal{E}_6$ -showing result time<br>$\mathcal{S}_6 w'_6 = \text{RS } \mathcal{E}_6 w'_6$ : $\mathcal{E}_6$ -showing result state<br>$\langle {}^1 \mathcal{E} \mathcal{E}'_6 w'_6 \dots {}^f \mathcal{E} \mathcal{E}'_6 w'_6 \rangle$ :<br>bear $a_3$ $h^{\text{ee}}_5$ -sucks ${}^\top k_4^\beta$ -milk from ${}^\top k_5^\alpha$ -mare<br>${}^P$ 'also': $\mathcal{E} \mathcal{E}_6 \sim ee_5$ (fox $a_1$ $h^{\text{ee}}_5$ -sucks in ${}^\top p_0$ )<br>${}^\top \mathcal{T}''_6 w_6 = \mathfrak{D}_{w_6} \text{RS}_{w_6} {}^1 \mathcal{E} \mathcal{E}'_6 w_6$ : aft 1st $\mathcal{E} \mathcal{E}'_6$ -stage |
| ~~~~~                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |
| $w_6 \in \text{Dom } \mathcal{E}_6 = \text{Ran } p_{\omega,6}$<br><ul style="list-style-type: none"> <li>       </li> <li>••</li> <li>•</li> <li>     </li> </ul>                                                                                                                                                           | <p>(<math>e'_6</math>-request/expectation of bear <math>a_3</math>)</p> $\mathcal{T}_6 w_6 = \mathfrak{D}_{w_6} \text{RS}_{w_6} e'_6$ : $e'_6$ -request result time<br>$\langle {}^1 \mathcal{E} \mathcal{E}_6 \dots {}^f \mathcal{E} \mathcal{E}_6 \rangle$ : fox $a_1$ & bear $a_3$ go along $ll_5$ -path<br>$\mathcal{E}_6 w_6$ : during ${}^f \mathcal{E} \mathcal{E}_6$ -result, fox $a_1$ shows bear $a_3$<br>bg $l_6$ of $ll_5$ -pth, plc of $s_5$ -sleep of ${}^\top k_5^\alpha$ -mare $a_2$<br>$\mathcal{T}'_6 w_6 = \mathfrak{D}_{w_6} \text{RS } \mathcal{E}_6 w_6$ : $\mathcal{E}_6$ -showing result time                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |

- 1.7 So... *if*<sub>1</sub>  
 sok  
*so*  
 $P[| d\exists\exists_1 \subseteq \mathbf{d}\omega\tau_2]; [\mathbf{t} \text{ eel } \mathbf{t} =_{\mathbf{d}\Omega} \mathbf{d}\omega\tau_2, \text{ ee} =_{\mathbf{d}\Omega} d\exists\exists_1];$   
 ...the two of them turned around...  
 s- -a *mf*<sub>1</sub>  
 "EE- -IND  
 $[h^{\varepsilon\varepsilon} | d\varepsilon\varepsilon =_{\mathbf{d}\Omega} {}^2h^{\varepsilon\varepsilon}]; [|\vartheta_{\mathbf{d}\Omega} {}^1d\varepsilon\varepsilon < \vartheta_{\mathbf{d}\omega} \mathbf{d}\varepsilon];$   
 hy-  
 33m-  
 $P[| 33m_{\mathbf{d}\Omega} \{\mathbf{d}\alpha + d\alpha\}]; [\mathbf{a} | \mathbf{a} = \mathbf{d}\alpha + d\alpha]; [|\text{AG } d\varepsilon\varepsilon =_{\mathbf{d}\Omega} \mathbf{d}\alpha];$   
 -áhket  
 -go.there  
 $[| d\eta^{\varepsilon\varepsilon}: \text{AG } go.along \mathbf{d}\pi\pi]; [|\text{}^f d\varepsilon\varepsilon \subseteq {}^1d\pi\pi];$   
 -e'  
 -EVT  
 $[|\text{}^1 d\varepsilon\varepsilon \subseteq_{\mathbf{d}\Omega} \mathbf{d}\tau]; [\mathbf{t} | \mathbf{t} =_{\mathbf{d}\Omega} \vartheta\text{RS } {}^1d\varepsilon\varepsilon]$   
 ...and went back to...  
 tanon' *if*<sub>2</sub>  
*and*  
 $[e | e \subseteq_{\mathbf{d}\Omega} \text{RS } {}^1d\varepsilon\varepsilon];$   
 y- on.s.a- *mf*<sub>2</sub>  
 XX- "EE- (s-) IND- (-wa)  
 $[| d\varepsilon =_{\mathbf{d}\Omega} {}^f d\varepsilon\varepsilon]; P[| d\varepsilon\varepsilon =_{\mathbf{d}\Omega} {}^2 d\eta^{\varepsilon\varepsilon}]; [|\vartheta_{\mathbf{d}\Omega} d\varepsilon < \vartheta_{\mathbf{d}\omega} \mathbf{d}\varepsilon];$   
 n-  
 33m-  
 $P[| 33m_{\mathbf{d}\Omega} \mathbf{d}\alpha]; [|\text{AG } d\varepsilon =_{\mathbf{d}\Omega} \mathbf{d}\alpha];$   
 -ew-  
 -arrive-  
 $P[| d\varepsilon\varepsilon: \text{AG } go.along_{\mathbf{d}\Omega} \mathbf{d}\pi\pi]; [|\text{}^f d\varepsilon = {}^f d\varepsilon\varepsilon];$   
 -'  
 -EVT  
 $[|\text{}^1 d\varepsilon \subseteq_{\mathbf{d}\Omega} \mathbf{d}\tau]; [\mathbf{t} | \mathbf{t} =_{\mathbf{d}\Omega} \vartheta\text{RS } d\varepsilon];$   
 áre' *fb*<sub>2</sub>  
*again*  
 $P[| d\varepsilon\varepsilon =_{\mathbf{d}\Omega} {}^2 d\eta^{\varepsilon\varepsilon}];$

1.7<sub>ff</sub> ...the place...

tsi- -nón ff<sub>2</sub>  
 D<sub>⊥</sub>- -*place/time*  
 [ $k^\pi$   $^1 d\pi\pi = dk^\pi\{d\varepsilon\}$ ]; [ $\Pi\{\varepsilon\} \subseteq dk^\pi\{\varepsilon\}$ ]

...where the mare was sleeping.

ne  
 D<sub>⊥</sub>  
 [ $d\alpha =_{d\Omega} dk^\alpha\{d\sigma\}$ ];

ko-  
 3s.3s-  
 $^P[3s \text{ AG } d\eta^\varepsilon, 3s \text{ dk}^\alpha\{d\eta^\varepsilon\}]$ ; [ $DA\{d\eta^\varepsilon\} = dk^\alpha\{d\eta^\varepsilon\}$ ];

hsaten- -s  
*ride.astride* -DUR  
 [ $d\eta^\varepsilon$ : AG *ride.astride* DA]; [ $dt \subseteq_{d\omega} d\eta^\varepsilon$ ];

ni yó-  
 of- 3sf<sub>U</sub>-  
 [ $d\pi =_{d\Omega} dk^\pi\{d\sigma\}$ ];  $^P[3sf_{d\Omega} \text{ dk}^\alpha\{d\sigma\}]$ ; [ $DA \text{ } d\sigma =_{d\Omega} dk^\alpha\{d\sigma\}$ ];

-tá'- -s  
 -*sleep*- -DUR  
 [ $d\sigma$ : DA *sleep*<sub>dΩ</sub>]; [ $dt \subseteq_{d\Omega} d\sigma$ ];

$w_0 \in {}^\top p_0$   
 $\vdots$

( $p_0$ -story worlds)

•  
 ...=====...  
 ••  
 |||||  
 ••  
 ||  
 •  
 |||||

$e'_6$ : bear  $a_3$  requests  $^1$ (and expects)  $\mathcal{E}_6$  dur RS  $e'_6$   
 $s_5$ :  ${}^\top k^\alpha$ -mare  $a_2$  sleeps at beg  $l_6$  of  $ll_5$ -path  
 $ee_5$ : fox  $a_1$   $h^{\varepsilon\varepsilon}$ -sucks  ${}^\top k^\beta$ -milk frm  ${}^\top k^\alpha$ -mare  $a_2$   
 $\mathcal{T}_6 w_0 = \mathfrak{D}_{w_0} \text{ RS}_{w_0} e'_6$ :  $e'_6$ -request result time  
 $ee_7 = \langle {}^1 \mathcal{E} \mathcal{E}_6 w_0, \dots {}^f \mathcal{E} \mathcal{E}_6 w_0 \rangle$ :  $p_0$ -realization of  $\mathcal{E} \mathcal{E}_6$   
 $t_7 = \mathfrak{D}_{w_0} \text{ RS } {}^1 ee_7$ : aft. 1st stg of  $ee_7$ -walk to  $l_6$   
 $e_7 = {}^f ee_7 (= {}^2 ee_7)$ : fox  $a_1$  & bear  $a_3$  arrive at  $l_6$   
 ${}^\top t'_7 = \mathfrak{D}_{w_0} \text{ RS}_{w_0} e_7$ : aft.  $e_7$ -arrival

$\mathcal{S}_6 = \langle \text{RS}_w \mathcal{E}_6 w : w \in \text{Ran } {}^\top p'_{\omega,6} \rangle$   
 $w'_6 \in \text{Dom } \mathcal{S}_6 = \text{Ran } {}^\top p'_{\omega,6}$

( $\mathcal{E}_6$ -result  $p'_{\omega,6}$ -desire of bear  $a_3$ )

|||||  
 ••  
 •  
 |||||  
 ==  
 •••  
 ||

$\mathcal{T}_6 w_6 = \mathfrak{D}_{w_6} \text{ RS}_{w_6} e'_6$ :  $e'_6$ -request result time  
 $\langle {}^1 \mathcal{E} \mathcal{E}_6, \dots {}^f \mathcal{E} \mathcal{E}_6 \rangle$ : fox  $a_1$  & bear  $a_3$  go along  $ll_5$ -path  
 $\mathcal{E}_6 w_6$ : during  ${}^f \mathcal{E} \mathcal{E}_6$ -result, fox  $a_1$  shows bear  $a_3$   
 bg  $l_6$  of  $ll_5$ -pth, w.  ${}^\top k^\alpha$ -mare  $a_2$  is  $s_5$ -sleeping  
 $\mathcal{T}'_6 w_6 = \mathfrak{D}_{w_6} \text{ RS } \mathcal{E}_6 w_6$ :  $\mathcal{E}_6$ -showing result time  
 $\mathcal{S}_6 w'_6 = \text{RS } \mathcal{E}_6 w'_6$ :  $\mathcal{E}_6$ -showing result state  
 $\langle {}^1 \mathcal{E} \mathcal{E}'_6 w'_6, \dots {}^f \mathcal{E} \mathcal{E}'_6 w'_6 \rangle$ :  
 bear  $a_3$   $h^{\varepsilon\varepsilon}$ -sucks  ${}^\top k^\beta$ -milk from  ${}^\top k^\alpha$ -mare  
 ${}^\top \mathcal{T}''_6 w_6 = \mathfrak{D}_{w_6} \text{ RS}_{w_6} {}^1 \mathcal{E} \mathcal{E}'_6 w_6$ : aft 1st  $\mathcal{E} \mathcal{E}'_6$ -stage



1.8<sup>3</sup> ...until*if*<sub>2</sub>

tsi=

D<sub>⊥</sub>=[el e = <sup>f</sup>dεε];

ni-

yó-

of-

3s<sub>U</sub>-[k<sup>τ</sup> dεε: k<sup>τ</sup>{ε} =<sub>dΩ</sub> ϑ{ε}]; <sup>P</sup>[| 3s dτ]; [| dκ<sup>τ</sup>{<sup>1</sup>dεε} =<sub>dΩ</sub> dτ];

re-

-‘

*distance-*

-CL

[| <sup>1</sup>dεε <<sub>dΩ</sub> dε]; [t| t =<sub>dΩ</sub> dκ<sup>τ</sup>{dε}]

...he was full

*mf*<sub>2</sub>

wa-

IND-

[| ϑ<sub>dΩ</sub> dε < ϑ<sub>dω</sub> dε];

hó-

3sm<sub>U</sub>-<sup>P</sup>[| 3sm dα]; [| DA {RS dε} =<sub>dΩ</sub> dα];

-hkwi’-

-*be.full*-<sup>P</sup>[| (dεε: AG *feed*<sub>dΩ</sub>), dε = <sup>f</sup>dεε]; [| RS dε: DA *feel.full*<sub>dΩ</sub>];

-ne’

-EVT

[| dε ⊆<sub>dΩ</sub> dτ]; [t| t =<sub>dΩ</sub> ϑRS dε];

---

|                            |                                                                                                                                                                         |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_0 \in {}^\top p_0$<br>⋮ | (p <sub>0</sub> -story worlds)<br>⋮                                                                                                                                     |
| •                          | $e'_6$ : bear $a_3$ requests <sup>1</sup> (and expects) $\mathcal{E}_6$ dur RS $e'_6$                                                                                   |
| ...=====...                | $s_5$ : ${}^\top k^{\alpha}_5$ -mare $a_2$ sleeps at beg $l_6$ of $ll_5$ -path                                                                                          |
| •••                        | $ee_5$ : fox $a_1$ $h^{\varepsilon\varepsilon}_5$ -sucks ${}^\top k^{\beta}_4$ -milk frm ${}^\top k^{\alpha}_5$ -mare $a_2$                                             |
|                            | $\mathcal{T}_6 w_0 = \mathfrak{D}_{w_0}$ RS $w_0$ $e'_6$ : $e'_6$ -request result time                                                                                  |
| ••                         | $ee_7 = \langle {}^1 \mathcal{E} \mathcal{E}_6 w_0, \dots {}^f \mathcal{E} \mathcal{E}_6 w_0 \rangle$ : p <sub>0</sub> -realization of $\mathcal{E} \mathcal{E}_6$      |
|                            | fox $a_1$ & bear $a_3$ go along $ll_6$ -path (to beg. $l_6$ ,<br>where ${}^\top k^{\alpha}_5$ -mare $a_2$ is $s_5$ -sleeping)                                           |
| •                          | $t_7 = \mathfrak{D}_{w_0}$ RS ${}^1 ee_7$ : aft. 1st stg of $ee_7$ -walk to $l_6$                                                                                       |
|                            | $e_7 = {}^f ee_7 (= {}^2 ee_7)$ : fox $a_1$ & bear $a_3$ arrive at $l_6$                                                                                                |
|                            | $t'_7 = \mathfrak{D}_{w_0}$ RS $w_0$ $e_7$ : aft. $e_7$ -arrival                                                                                                        |
| •                          | $t_8 = \mathfrak{D}_{w_0}$ $e_8$ : right after $e_7$ -arrival                                                                                                           |
|                            | $e_8 = \text{BG}_{w_0} \{ \text{RS}_{w_0} e_7 \} = {}^1 \mathcal{E} \mathcal{E}'_6 w_0$ :                                                                               |
| •                          | beg of $e_7$ -res state, bear $a_3$ starts $\mathcal{E} \mathcal{E}_6$ -sucking                                                                                         |
|                            | $t'_8 = \mathfrak{D}_{w_0}$ RS $w_0$ $e_8$ : aft. 1st stg of $\mathcal{E} \mathcal{E}'_6$ -sucking                                                                      |
| •••                        | $ee_8 = \langle {}^1 \mathcal{E} \mathcal{E}'_6 w'_0, \dots {}^f \mathcal{E} \mathcal{E}'_6 w'_0 \rangle$ : p <sub>0</sub> -realization of $\mathcal{E} \mathcal{E}'_6$ |
| •                          | bear $a_3$ $h^{\varepsilon\varepsilon}_5$ -sucks ${}^\top k^{\beta}_4$ -milk from ${}^\top k^{\alpha}_5$ -mare                                                          |
|                            | $e'_8 = {}^f ee_8$ : end of $ee_8$ -sucking,                                                                                                                            |
| •                          | in $e'_8$ -result state bear $a_3$ feels full                                                                                                                           |
|                            | $t''_8 = \mathfrak{D}_{w_0}$ $e'_8$ : $e'_8$ -now                                                                                                                       |
|                            | ${}^\top t'''_8 = \mathfrak{D}_{w_0}$ $e'_8$ : aft. $e'_8$ -end of $ee_8$ -sucking                                                                                      |

$\mathcal{S}_6 = \langle \text{RS}_w \mathcal{E}_6 w : w \in \text{Ran } {}^\top p'_{\omega,6} \rangle$   
 $w'_6 \in \text{Dom } \mathcal{S}_6 = \text{Ran } {}^\top p'_{\omega,6}$

( $\mathcal{E}_6$ -result  $p'_{\omega,6}$ -desire of bear  $a_3$ )

|     |                                                                                                                                                                                        |
|-----|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|     | $\mathcal{T}_6 w_6 = \mathfrak{D}_{w_6}$ RS $w_6$ $e'_6$ : $e'_6$ -request result time                                                                                                 |
| ••  | $\langle {}^1 \mathcal{E} \mathcal{E}_6, \dots {}^f \mathcal{E} \mathcal{E}_6 \rangle$ : fox $a_1$ & bear $a_3$ go along $ll_5$ -path                                                  |
| •   | $\mathcal{E}_6 w_6$ : during ${}^f \mathcal{E} \mathcal{E}_6$ -result, fox $a_1$ shows bear $a_3$<br>bg $l_6$ of $ll_5$ -pth, w. ${}^\top k^{\alpha}_5$ -mare $a_2$ is $s_5$ -sleeping |
|     | ${}^\top \mathcal{T}'_6 w_6 = \mathfrak{D}_{w_6}$ RS $\mathcal{E}_6 w_6$ : $\mathcal{E}_6$ -showing result time                                                                        |
| ==  | $\mathcal{S}_6 w'_6 = \text{RS } \mathcal{E}_6 w'_6$ : $\mathcal{E}_6$ -showing result state                                                                                           |
| ••• | $\langle {}^1 \mathcal{E} \mathcal{E}'_6 w'_6, \dots {}^f \mathcal{E} \mathcal{E}'_6 w'_6 \rangle$ :                                                                                   |
| •   | bear $a_3$ $h^{\varepsilon\varepsilon}_5$ -sucks ${}^\top k^{\beta}_4$ -milk from ${}^\top k^{\alpha}_5$ -mare                                                                         |
|     | P <sub>6</sub> 'also': $\mathcal{E} \mathcal{E}_6 \sim ee_5$ (fox $a_1$ $h^{\varepsilon\varepsilon}_5$ -sucks in ${}^\top p_0$ )                                                       |
|     | ${}^\top \mathcal{T}''_6 w_6 = \mathfrak{D}_{w_6}$ RS $w_6$ ${}^1 \mathcal{E} \mathcal{E}'_6 w_6$ : aft 1st $\mathcal{E} \mathcal{E}'_6$ -stage                                        |

## §2. *Fox makes a proposal*

2.1<sup>1</sup> The fox [then] said:

wa-

IND

[*e*]; [*!*  $\vartheta_{d\Omega} d\varepsilon < \vartheta_{d\omega} \mathbf{d}\varepsilon$ ];

hen-

3sm-

<sup>P</sup>[*!*  $3sm_{d\Omega} (\mathbf{d}\alpha_1 - \mathbf{d}\alpha)$ ]; [*a* *a* = ( $\mathbf{d}\alpha_1 - \mathbf{d}\alpha$ )]; [*!* AG  $d\varepsilon =_{d\Omega} \mathbf{d}\alpha$ ];

-ron-

-say

[*!*  $d\varepsilon$ : AG *speak*<sub>dΩ</sub>];

-'

-EVT

[*!*  $d\varepsilon \subseteq_{d\Omega} \mathbf{d}\tau$ ]; [*t* *t* =<sub>dΩ</sub>  $\vartheta_{RS} d\varepsilon$ ];

ne

-tsitsho

D<sub>τ</sub>

-fox

[*k*<sup>α</sup>  $\mathbf{d}\alpha =_{d\Omega} k^\alpha \{d\varepsilon\}$ ]; [*!* *fox*  $d\kappa^\alpha$ ];

*mf*

*ff*

2.1<sup>2</sup> “(shift to fox’s voice)

[*e* *e* =  $d\varepsilon$ ]; [*t* *t* =<sub>dΩ</sub>  $\vartheta \mathbf{d}\varepsilon$ ];

It might...<sup>4</sup>

toka’-

-nonw

-a

maybe-

-plc/tm

-CL

[*p*<sub>ω</sub> *!*  $\mathcal{E} \subseteq_{p\omega} \vartheta_{RS} \mathbf{d}\varepsilon$ ]; [*A* *S* = RS  $d\varepsilon$ ]; [*T* *T* =  $\vartheta d\omega\sigma$ ];

...be nice...

yo-

3s<sub>U</sub>-

<sup>P</sup>[*!*  $3s \mathbf{d}\omega\Omega$ ]; [*!* Dom  $d\omega\sigma =_{d\Omega} \mathbf{d}\omega\Omega$ ];

-yáner-

-be.nice-

[*!*  $d\omega\sigma$  nice.for DA];

-e’

-STA

[*!*  $\mathbf{d}\omega\tau \subseteq_{d\omega\Omega} d\omega\sigma$ ];

*if*

*ib*

<sup>4</sup> • Any state realizing  $d\omega\sigma$  is nice for the experiencer

$d\omega\sigma$  nice.for DA  $:= \lambda i. \forall w \in \text{Dom } d\omega\sigma, \exists s: s = d\omega\sigma, w \wedge \text{nice.for}_w(s, \text{DA}_w s)$

2.1<sup>3</sup> ...to carry her off (bodily)...<sup>5</sup>

ne

mf

D<sub>T</sub>[ $\mathcal{T} | \mathcal{T} =_{d\omega\Omega} \vartheta \text{RS } \mathbf{d}\varepsilon$ ];

y-

aon-

sa-

XX-

OPT-

"EE-

[ $\mathcal{E}\mathcal{E} \mathcal{L} \overset{f}{\mathcal{E}\mathcal{E}} \subseteq \mathcal{L}$ ]; [ ${}^1 d\exists \subseteq_{d\omega\Omega} \vartheta \text{RS } \mathbf{d}\varepsilon$ ]; [ ${}^1 | \text{RS } \mathbf{d}\varepsilon$ : DA *want*<sub>d $\omega$</sub>   $d\exists$ ]; [ $d\exists = \overset{f}{d\exists}$ ];

yeteni-

12.3sf-

<sup>P</sup>[ $\mathbf{a} | 12_{d\Omega} \mathbf{a}$ ,  $3sf_{d\Omega} d\alpha$ ]; [ ${}^1 \text{AG } d\exists = \mathbf{d}\alpha$ , DA  $d\exists = d\alpha$ ];

ya't-

-enhaw-

body-

-carry-

[ $k^\beta | k^\beta \text{ body.of } d\alpha$ ]; [ $d\exists$ : AG *carry*  $d\kappa^\beta$ ];

-'

-EVT

[ ${}^1 d\exists \subseteq_{d\omega\Omega} \mathbf{d}\omega\tau$ ]; [ $\mathcal{T} | \mathcal{T} = \vartheta \text{RS } {}^1 d\exists$ ]; $w_0 \in {}^T p_0$   
⋮ $(p_0\text{-story worlds})$   
⋮

•••

 $ee_8 = \langle {}^1 \mathcal{E}\mathcal{E}'_6 w'_0 \dots \overset{f}{\mathcal{E}\mathcal{E}'_6} w'_0 \rangle$ :  $p_0$ -realization of  $\mathcal{E}\mathcal{E}'_6$ bear  $a_3$   $h^{\varepsilon\varepsilon}_5$ -sucks  ${}^T k^\beta_4$ -milk from  ${}^T k^\alpha_5$ -mare

•

 $e'_8 = \overset{f}{ee}_8$ : end of  $ee_8$ -sucking,in  $e'_8$ -result state bear  $a_3$  feels full

||

 $t''_8 = \vartheta_{w_0} e'_8$ :  $e'_8$ -now

|||

 $t'''_8 = \vartheta_{w_0} e'_8$ : aft.  $e'_8$ -end of  $ee_8$ -sucking

•

 ${}^T e_1$ : fox  $a_1$  speaks about  $\mathcal{E}_1$  (to bear  $a_3$ )

|||||

 $t_1 = \vartheta_{w_0} \text{RS}_{w_0} e_1$ :  $e_1$ -result time

|

 ${}^T t'_1 = \vartheta_{w_0} e_1$ :  $e_1$ -now $w_1 \in \text{Dom } \mathcal{E}_1 = {}^T p_{\omega,1} w_0$  $(e_1\text{-suggested desirable possibility})$ 

|||||||

 $\vartheta_{w_1} \text{RS}_{w_1} e_1$ : time of  ${}^T e_1$ -desired result

•

 $\mathcal{E}_1 w_1 = \overset{f}{\mathcal{E}\mathcal{E}}_1 w_1$ : end of  $\mathcal{E}\mathcal{E}_1$ -carrying,

=====

 $\mathcal{S}_1 w_1 = \text{RS}_{w_1} \mathcal{E}_1 w_1$ : result state of  $\mathcal{E}\mathcal{E}_1$ -carrying,nice for dat = fox  $a_1$  + bear  $a_3$ 

|||||||

 ${}^T \mathcal{T}_1 w_1 = \vartheta_{w_1} \mathcal{S}_1 w_1$ : time of  $\mathcal{S}_1$  (desired res state)

|||||||

 $\mathcal{T}'_1 w_1 = \vartheta_{w_1} \text{RS}_{w_1} e_1$ : time of  ${}^T e_1$ -desired result

••

 $\langle {}^1 \mathcal{E}\mathcal{E}_1 w_1 \dots \overset{f}{\mathcal{E}\mathcal{E}}_1 w_1 \rangle$ : fox  $a_1$  + bear  $a_3$  carry $k^\beta_1$ -body of mare  $a_2$  off to  $\mathcal{L}_1 w_1$ 

||

 ${}^T \mathcal{T}''_1 w_1 = \vartheta_{w_1} \text{RS}_{w_1} {}^1 \mathcal{E}\mathcal{E}_1 w_1$ : during  $\mathcal{E}\mathcal{E}_1$ -carrying<sup>5</sup> • Any realization of the final stage of  $\mathcal{E}\mathcal{E}$  occurs within  $\mathcal{L}$  $\overset{f}{\mathcal{E}\mathcal{E}} \subseteq \mathcal{L}$ :=  $\lambda i. \forall w \in \text{Dom } \overset{f}{\mathcal{E}\mathcal{E}} \exists e, l: e = [\overset{f}{\mathcal{E}\mathcal{E}}]w \wedge l = \mathcal{L}w \wedge \Pi_w e \subseteq l$ •  $d\exists$  is a process-chain of stage concepts such that in any realization of any stage the agent carries  $d\kappa^\beta$  $d\exists$ : AG *carry*  $d\kappa^\beta$ :=  $\lambda i. \text{process } d\exists_i \wedge \forall \mathcal{E} \in d\exists_i \forall w \in \text{Dom } \mathcal{E}: \text{carry}_w(\mathcal{E}w, \text{AG}_w \mathcal{E}w, d\kappa^\beta_i w(\mathcal{E}w))$

2.1<sup>4</sup> ...then for ever it would make her our milking mare.<sup>6</sup>

khná:'a

then

[ $\mathcal{I} \mathcal{I} =_{d\omega\Omega} \vartheta RS d\exists$ ];

if

kyótkon

always

[ $h^{\varepsilon\varepsilon} | h^{\varepsilon\varepsilon} =_{d\omega\Omega} (d\eta^{\varepsilon\varepsilon} | d\omega\tau)$ ]; [ $\mathcal{D} | \mathcal{D} \subseteq_{d\omega\Omega} d\eta^{\varepsilon\varepsilon}$ ]; [ $^1 | d\eta^{\varepsilon\varepsilon} \subseteq_{d\omega\Omega} d\theta$ ]

n=

é:'e

ib

D<sub>τ</sub>=

(s)he

[ $| d\alpha =_{d\Omega} \mathbf{d}\kappa^\alpha \{d\varepsilon\varepsilon\}$ ]; [ $^P | \exists s_{d\omega\Omega} d\alpha$ ]; [ $| d\alpha =_{d\omega\Omega} \mathbf{d}\kappa^\alpha \{d\eta^{\varepsilon\varepsilon}\}$ ]

en-

HYP-

[ $| d\omega\tau =_{d\omega\Omega} \vartheta RS d\exists$ ]; [ $^1 | RS d\exists$ : DA *expect*  $d\omega\Omega$ ];

mf

yonkeni-

12<sub>U</sub>-

[ $^P | 12_{d\Omega} \mathbf{d}\alpha$ ]; [ $| DA d\omega\sigma =_{d\omega\Omega} \mathbf{d}\alpha$ ];

nahskwa-

-yen-

animal.of-

-be(.at)-

[ $| d\omega\sigma$ :  $\mathbf{d}\kappa^\alpha$  *animal.of* DA]; [ $| DA d\omega\sigma \neq \mathbf{d}\kappa^\alpha \{d\omega\sigma\}$ ];

-(h)t

-(h)ak

-cause

-itr

[ $| d\omega\sigma = RS d\exists$ ]; [ $| \vartheta d\omega\sigma \subseteq d\eta^{\varepsilon\varepsilon}$ ];

-e'

-EVT

[ $| d\omega\tau \subseteq_{d\omega\Omega} d\eta^{\varepsilon\varepsilon}$ ]; [ $\mathcal{D} | \mathcal{D} = \vartheta RS \ ^1 d\eta^{\varepsilon\varepsilon}$ ];

” (end fox’s voice)

[ $| \mathbf{t} | \mathbf{t} =_{d\Omega} \vartheta RS \mathbf{d}\varepsilon$ ]; [ $| \mathbf{e} | \mathbf{e} = \mathbf{d}\varepsilon_1$ ];

- 
- <sup>6</sup> • In any  $d\omega\Omega$ -accessible world,  $h^{\varepsilon\varepsilon}$  is the restriction of  $d\eta^{\varepsilon\varepsilon}$ -habit to  $d\eta^{\varepsilon\varepsilon}$ -processes occurring during  $d\omega\tau$   
 $h^{\varepsilon\varepsilon} =_{d\omega\Omega} (d\eta^{\varepsilon\varepsilon} | d\omega\tau) \quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\Omega_i \forall w' \in d\omega\Omega_i w$ :  
 $h^{\varepsilon\varepsilon} w' = \langle d\eta^{\varepsilon\varepsilon}_i w' t : t \in \text{Dom } d\eta^{\varepsilon\varepsilon} w' \ \& \ t \subseteq d\omega\tau_i w \rangle$
- In any  $d\omega\Omega$ -accessible world, any  $\mathcal{D}$ -time is a  $d\eta^{\varepsilon\varepsilon}$ -frame,<sup>1</sup> (and any  $d\eta^{\varepsilon\varepsilon}$ -frame is a  $\mathcal{D}$ -time)  
 $\mathcal{D} \subseteq_{d\omega\Omega} d\eta^{\varepsilon\varepsilon} \quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\Omega_i \forall w' \in d\omega\Omega_i w : \mathcal{D} w' \subseteq \text{Dom } d\eta^{\varepsilon\varepsilon}_i w'$   
 $d\eta^{\varepsilon\varepsilon} \subseteq_{d\omega\Omega} \mathcal{D} \quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\Omega_i \forall w' \in d\omega\Omega_i w : \text{Dom } d\eta^{\varepsilon\varepsilon}_i w' \subseteq \mathcal{D} w'$
- In any  $d\omega\Omega$ -accessible world,  $d\alpha$  instantiates  $\mathbf{d}\kappa^\alpha$  at every stage of any  $d\eta^{\varepsilon\varepsilon}$ -process  
 $d\alpha =_{d\omega\Omega} \mathbf{d}\kappa^\alpha \{d\eta^{\varepsilon\varepsilon}\} \quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\Omega_i \forall w' \in d\omega\Omega_i w \forall e \in \text{Ran } d\eta^{\varepsilon\varepsilon}_i w \forall e \in ee : d\alpha_i = \mathbf{d}\kappa^\alpha_i w'e$
- The experiencer of any realization of the result state of  $d\exists$  expects to be in a  $d\omega\Omega$ -accessible world  
 $RS d\exists$ : DA *expect*  $d\omega\Omega \quad := \quad \lambda i. \forall w \in \text{Dom } d\exists_i \exists s : s = RS_w d\exists_i w \wedge \text{expect}_w(s, DA_w s, d\omega\Omega_i w)$
- In any state realizing  $d\omega\sigma$ , there is a  $\mathbf{d}\kappa^\alpha$ -animal belonging to the experiencer, who is not that animal  
 $d\omega\sigma$ :  $\mathbf{d}\kappa^\alpha$  *animal.of* DA  $\quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\sigma_i \exists s : s = d\omega\sigma_i w \wedge \text{animal.of}_w(s, \mathbf{d}\kappa^\alpha_i w s, DA_w s)$   
 $DA d\omega\sigma \neq \mathbf{d}\kappa^\alpha \{d\omega\sigma\} \quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\sigma_i \exists s : s = d\omega\sigma_i w \wedge DA_w s \neq \mathbf{d}\kappa^\alpha_i w s$
- In any  $d\omega\sigma$ -world, the time of  $d\omega\sigma$  is included in the period ( $\cup_\tau$ ) spanned by  $d\eta^{\varepsilon\varepsilon}$ -frames  
 $\vartheta d\omega\sigma \subseteq d\eta^{\varepsilon\varepsilon} \quad := \quad \lambda i. \forall w \in \text{Dom } d\omega\sigma_i \exists s : s = d\omega\sigma_i w \wedge \vartheta_w s \subseteq \cup_\tau \text{Dom } d\eta^{\varepsilon\varepsilon}_i w$

|                            |                                                                                                                                                                                                                                                                         |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_0 \in {}^\top p_0$<br>⋮ | (p <sub>0</sub> -story worlds)<br>⋮                                                                                                                                                                                                                                     |
| •••                        | $ee_8 = \langle {}^1 \mathcal{E} \mathcal{E}'_6 w'_0 \dots {}^f \mathcal{E} \mathcal{E}'_6 w'_0 \rangle$ : p <sub>0</sub> -realization of $\mathcal{E} \mathcal{E}'_6$<br>bear $a_3$ $h^{\text{ee}}_5$ -sucks ${}^\top k^\beta_4$ -milk from ${}^\top k^\alpha_5$ -mare |
| •                          | $e'_8 = {}^f ee_8$ : end of $ee_8$ -sucking,<br>in $e'_8$ -result state bear $a_3$ feels full                                                                                                                                                                           |
|                            | $t''_8 = \mathfrak{D}_{w_0} e'_8$ : $e'_8$ -now                                                                                                                                                                                                                         |
|                            | $t'''_8 = \mathfrak{D}_{w_0} e'_8$ : aft. $e'_8$ -end of $ee_8$ -sucking                                                                                                                                                                                                |
| •                          | $e_1$ : fox $a_1$ speaks about $\mathcal{E}_1$ (to bear $a_3$ )                                                                                                                                                                                                         |
|                            | $t_1 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_1$ : $e_1$ -result time                                                                                                                                                                                                     |
|                            | $t'_1 = \mathfrak{D}_{w_0} e_1$ : $e_1$ -now                                                                                                                                                                                                                            |
|                            | $t''_1 = \mathfrak{D}_{w_0} \text{RS}_{w_0} e_1 = t_1$ : $e_1$ -result time                                                                                                                                                                                             |

|                                                                |                                                                                                                                                                                                                              |
|----------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $w_1 \in \text{Dom } \mathcal{E}_1 = {}^\top p_{\omega,1} w_0$ | (e <sub>1</sub> -suggested desirable possibility)                                                                                                                                                                            |
|                                                                | $\mathfrak{D}_{w_1} \text{RS}_{w_1} e_1$ : time of ${}^\top e_1$ -desired result                                                                                                                                             |
| •                                                              | $\mathcal{E}_1 w_1 = {}^f \mathcal{E} \mathcal{E}_1 w_1$ : end of $\mathcal{E} \mathcal{E}_1$ -carrying,                                                                                                                     |
| =====                                                          | $\mathcal{S}_1 w_1 = \text{RS}_{w_1} \mathcal{E}_1 w_1$ : result state of $\mathcal{E} \mathcal{E}_1$ -carrying,<br>nice for dat = fox $a_1$ + bear $a_3$<br>${}^\top k^\alpha_5$ -mare $a_2$ is an animal of (owned by) dat |
|                                                                | $\mathcal{T}_1 w_1 = \mathfrak{D}_{w_1} \mathcal{S}_1 w_1$ : time of $\mathcal{S}_1$ (desired res state)                                                                                                                     |
|                                                                | $\mathcal{T}'_1 w_1 = \mathfrak{D}_{w_1} \text{RS}_{w_1} e_1$ : time of ${}^\top e_1$ -desired result                                                                                                                        |
| ••                                                             | $\langle {}^1 \mathcal{E} \mathcal{E}_1 w_1 \dots {}^f \mathcal{E} \mathcal{E}_1 w_1 \rangle$ : fox $a_1$ + bear $a_3$ carry<br>$k^\beta_1$ -body of mare $a_2$ off to $\mathcal{L}_1 w_1$                                   |
|                                                                | $\mathcal{T}''_1 w_1 = \mathfrak{D}_{w_1} \text{RS}_{w_1} {}^1 \mathcal{E} \mathcal{E}_1 w_1$ : during $\mathcal{E} \mathcal{E}_1$ -carrying                                                                                 |
|                                                                | $\mathcal{T}_1 w_1 = \mathfrak{D}_{w_1} \text{RS}_{w_1} \mathcal{E}_1 w_1$ : time of desired res state                                                                                                                       |
| ••...••                                                        | $h^{\text{ee}}_1 w_1 = \{h^{\text{ee}}_5 w_1 t : t \in \mathcal{T}_1 w_1\}$<br>agt $h^{\text{ee}}_5$ -sucks from $k^\alpha_5$ -mare $a_2$ dur ${}^\top \mathcal{T}_1 w_1$                                                    |
| ...                                                            | $\mathcal{D}_1 w_1 = \text{Dom } h^{\text{ee}}_1 w_1$ : $h^{\text{ee}}_1$ -milk.sucking times                                                                                                                                |
| ...                                                            | ${}^\top \mathcal{D}'_1 w_1 = \{\mathfrak{D}_{w_1} \text{RS}_{w_1} {}^1 ee : ee \in \text{Ran } h^{\text{ee}}_1 w_1\}$<br>during $h^{\text{ee}}_1$ -milk.sucking (1st stg-after.times)                                       |